

New constraints on the shear wave velocity structure of the Ivrea geophysical body from seismic ambient noise tomography (Ivrea-Verbano Zone, Alps)

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SUMMARY

We performed seismic ambient noise tomography to investigate the shallow crustal structure around the Ivrea geophysical body (IGB) in the Ivrea-Verbano Zone (IVZ). We achieved higher resolution with respect to previous tomographic works covering the Western Alps, by processing seismic data collected by both permanent and temporary seismic networks (61 broad-band seismic stations in total). This included IvreaArray, a temporary, passive seismic experiment designed to investigate the IVZ crustal structure. Starting from continuous seismic ambient noise recordings, we measured and inverted the dispersion of the group velocity of surface Rayleigh waves (fundamental mode) in the period range 4–25 s. We obtained a new, 3-D v_S model of the IVZ crust via the stochastic neighbourhood algorithm (NA), with the highest resolution between 3 to 40 km depth. The fast and shallow shear wave velocity anomaly associated with the IGB presents velocities of 3.6 km s^{-1} directly at the surface, in remarkable agreement with the location of the exposed lower-to-middle crustal and mantle outcrops. This suggests a continuity between the surface geological observations and the subsurface geophysical anomalies. The fast IGB structure reaches v_S of 4 km s^{-1} at 20–25 km depth, at the boundary between the European and Adriatic tectonic plates, and in correspondence with the earlier identified Moho jump in the same area. The interpretation of a very shallow reaching IGB is further supported by the comparison of our new results with recent geophysical investigations, based on receiver functions and gravity anomaly data. By combining the new geophysical constraints and the geological observations at the surface, we provide a new structural interpretation of the IGB, which features lower crustal and mantle rocks at upper crustal depths. The comparison of the obtained v_S values with the physical properties from laboratory analysis of local rock samples suggests that the bulk of the IGB consists of a combination of mantle peridotite, ultramafic and lower crustal rocks, bound in a heterogeneous structure. These new findings, based on v_S tomography, corroborate the recent interpretation for which the Balmuccia peridotite outcrops are continuously linked to the IGB structure beneath. The new outcomes contribute to a multidisciplinary framework for the interpretation of the forthcoming results of the scientific drilling project DIVE.

DIVE aims at probing the lower continental crust and its transition to the mantle, with two ongoing and one future boreholes (down to 4 km depth) in the IVZ area, providing new, complementary information on rock structure and composition across scales. In this framework, we constrain the upper crustal IGB geometries and lithology based on new evidence for v_S , connecting prior crustal knowledge to recent active seismic investigations.

Key words: Continental crust; Seismic noise; Seismic tomography; Continental tectonics; compressional; Crustal structure.

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1 INTRODUCTION

The Ivrea-Verbano Zone (IVZ) is located along the inner arc of the Western Alps (Europe) and represents a long-recognized, open-air geological and geophysical laboratory for the study of both the Earth's crust and mantle. Bounded to the north by the Insubric segment of the Periadriatic Line (PL, Schmid *et al.* 1989), the IVZ lies at the frontier between the European and the Adriatic tectonic plates (Schmid *et al.* 2004; Petri *et al.* 2019), which were involved in the Alpine continental collision that began at *ca.* 35 Ma (Handy *et al.* 2010, 2015).

The IVZ exposes lower-to-middle crustal composition rocks outcropping at the surface, and is regarded as an almost-unique and nearly complete cross-section of the continental crust (Fig. 1, Fountain 1976; Zingg *et al.* 1990; Khazanehdari *et al.* 2000). It also exposes mantle peridotite rocks; among these, the Balmuccia peridotite is the largest outcropping mantle unit at the surface (Fig. 1), bounded by a mafic lower crustal complex (e.g. Rivalenti *et al.* 1975, 1981; Quick *et al.* 1995, 2003).

In this study, we focus on the high-density high seismic-velocity anomaly beneath the IVZ surface, which extends up to shallow depths (i.e. below 10 km depth) known as the Ivrea geophysical body (IGB, e.g. Kissling *et al.* 1984). We aim to image and model the IGB structure and surroundings in terms of absolute shear wave velocity (v_S). The IGB constitutes the root of the IVZ and it is closely related (if not directly linked) to the exposed geological units at the surface. It is characterized by an anomalously dense and seismically fast structure (e.g. Berckhemer 1968; Bürki 1990; Solarino *et al.* 2018; Scarponi *et al.* 2020, 2021), which extends along the whole inner arc of the Western Alps in correspondence with the European–Adriatic continental collision boundary. This anomaly features along-strike variations, especially in the depth of its uppermost structure, and potentially outcrops at the surface in the IVZ. Interpreted as a sliver of Adriatic lower lithosphere (e.g. Schmid *et al.* 2017), and emplaced at shallow depth during the European–Adriatic tectonic collision, the IGB has been the subject of multiple geophysical investigations since the early work of Niggli (1947).

The IGB was first imaged via active refraction and reflection seismic experiments (e.g. Closs & Labrouste 1963; Berckhemer 1968; Ansgorge 1979; Thouvenot *et al.* 1990), which provided new geophysical evidences for geodynamic and tectonic interpretation of the Alps (e.g. Schmid & Kissling 2000) and structural constraints for the development of IGB density models via gravity anomaly analysis (e.g. Berckhemer 1968; Kissling *et al.* 1984; Bayer *et al.* 1989; Bürki 1990). These studies both exploited and showed the technical limitations of active seismic experiments, especially in imaging the strongly and laterally varying crustal structure associated with the IGB (Kissling 1993), beneath a terrain that is challenging to instrument in an optimal manner (topographic map in Fig. S0, Supporting Information).

The increasing seismic data availability in the Alps (e.g. Hetényi *et al.* 2018) and the advent of modern seismic tomographic techniques allowed to image the western Alps and the IGB at regional scales with improving resolution, by exploiting both local (e.g. Paul *et al.* 2001; Diehl *et al.* 2009; Solarino *et al.* 2018) and teleseismic earthquake events (e.g. Lippitsch *et al.* 2003; Kissling *et al.* 2006), traveltimes analysis (e.g. De Franco *et al.* 1997) and seismic ambient noise recordings (e.g. Kästle *et al.* 2018; Lu *et al.* 2018; Zhao *et al.* 2020; Nouibat *et al.* 2022). Seismic receiver functions (RF) were also employed to map the IGB geometry and its physical properties at key locations along the European–Adriatic collision boundary

(e.g. Zhao *et al.* 2015; Salimbeni *et al.* 2020; Colavitti *et al.* 2022; Paul *et al.* 2022).

Nevertheless, the data sets in these works did not have sufficient resolution for a detailed investigation of the local IGB structure and physical properties beneath the IVZ geological units, nor to address key open questions such as: what is the connection between the shallow IGB anomaly and the outcropping rocks of lower-to-middle crustal composition in the IVZ? How do the structure and the composition of the IGB vary with depth?

Establishing whether a continuous link between IVZ surface geological units and shallow geophysical anomalies exists or not is key to better understand the IVZ's tectonic emplacement, investigate the existence and the status of a former Moho and, more generally, to study how crustal-scale deformation occurs in continental collision zones.

Multiple studies have taken steps towards these questions recently, as forerunners of the scientific drilling project DIVE (www.dive2ivrea.org, Pistone *et al.* 2017). Benefiting from new seismic and gravity data (Hetényi *et al.* 2017; Scarponi *et al.* 2020), recent multidisciplinary geophysical investigations provided new constraints on the IGB 3-D density distribution, geometry and composition at intracrustal to kilometric scales beneath in the IVZ. These have clearly delineated the contours of a denser and seismically faster structure, reaching as shallow as 1 ± 1 km depth below sea level (Scarponi *et al.* 2020, 2021), with physical properties in agreement with ultramafic mantle rock types. Pistone *et al.* (2020) investigated the composition of the IGB at depth by comparing petrophysical modelling with density (Scarponi *et al.* 2020) and larger scale v_P constraints (Diehl *et al.* 2009), pointing at a predominantly lower crustal body for the IGB. However, no constraints on v_S were available for the same analysis (Pistone *et al.* 2020).

Recent high-resolution, shallow v_P tomography from active source seismics suggests that the IVZ Balmuccia peridotite represents the tip of a wider, buried mantle body, which is continuously linked to the IGB at depth (Ryberg *et al.* 2023). This recent finding favours the idea of a fossil crustal–mantle transition zone being close to and at the surface (e.g. Rivalenti *et al.* 1975; Zingg *et al.* 1990), against the interpretation of isolated peridotite lenses in Balmuccia (e.g. Quick *et al.* 2003). However, Ryberg *et al.* (2023) provide local v_P constraints down to only *ca.* 3 km depth below the surface. To follow up on investigating the structural link by imaging bulk seismic properties in 3-D, and to constrain the IGB composition as well, within the same framework of the most recent passive geophysical investigations (e.g. Scarponi *et al.* 2020, 2021), we performed seismic ambient noise tomography (ANT) in the area.

The ANT analysis provides new, 3-D high-resolution geophysical constraints on absolute v_S beneath the IVZ at intracrustal scales, with the highest resolution between *ca.* 3 km and a maximum depth of 40 km.

2 DATA

We collected continuous broad-band seismic data, organized in daily files, from the permanent seismic networks of Switzerland and Italy (FDSN network codes IV, GU, MN, CH; Fig. 1—see Data Availability statement for full data reference). To improve the data coverage and the resolution with respect to the previous tomographic studies constraining v_S across the Western Alps, we also processed the seis-

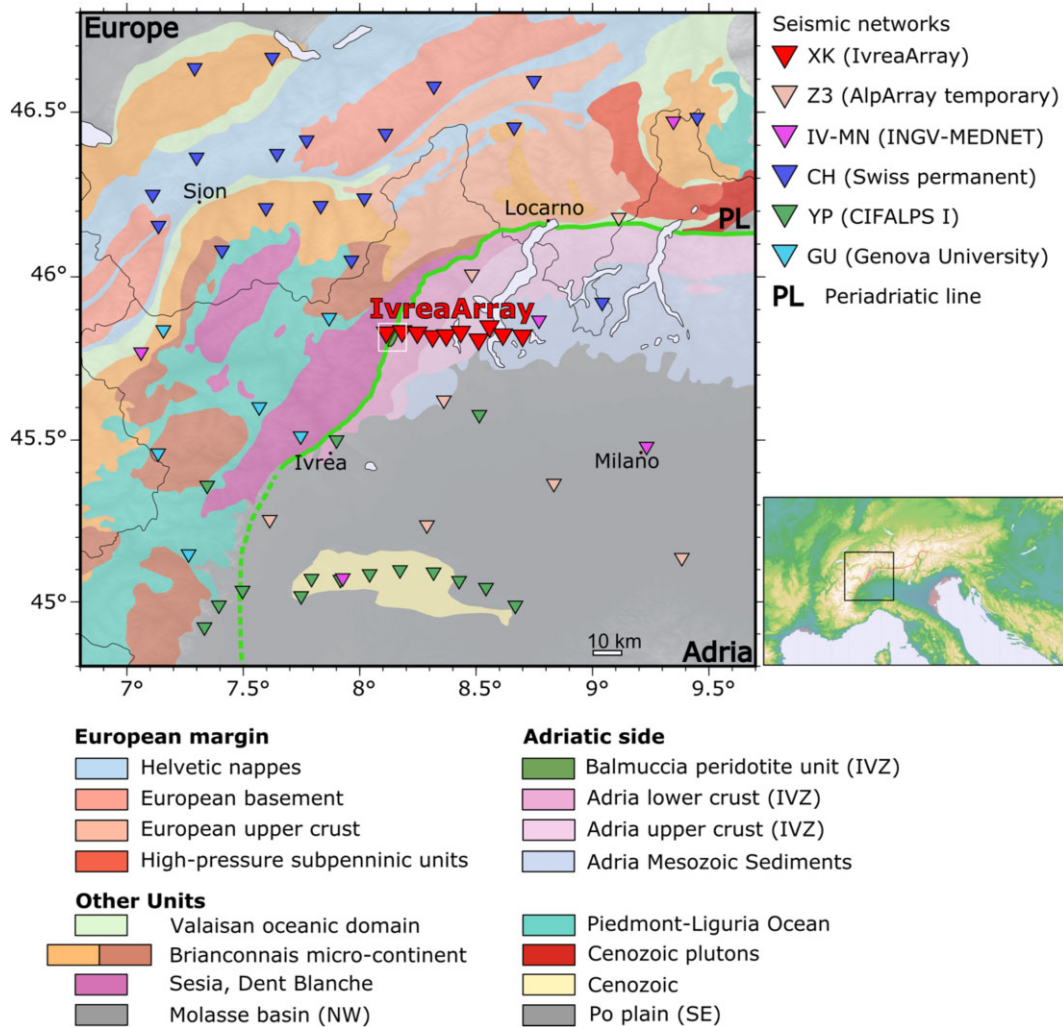


Figure 1. Tectonic map of the IVZ and surrounding region in the Western Alps, with simplified tectonic units after Schmid *et al.* (2004). The PL in green separates the main European and Adriatic tectonic domains at the surface. The seismic stations used for this study are shown as triangles, coloured according to the respective operating network (see the legend). The white dashed rectangle to the western portion of IvreaArray indicates the location of the Balmuccia mantle peridotite outcrop.

mic data collected from the passive seismic experiment CIFALPS I (Zhao *et al.* 2016, network code YP), and the temporary seismic stations operated in the frame of the cooperative AlpArray project (Hetényi *et al.* 2018, network code Z3). These data sets were merged with the seismic recordings of the IvreaArray passive experiment (Hetényi *et al.* 2017; Scarponi *et al.* 2021, Fig. 1), which was established to better image the IGB in the IVZ. IvreaArray operated 10 broad-band seismic stations from the MOBNET pool of the IGCAS (Institute of Geophysics of the Czech Academy of Sciences, <https://www.ig.cas.cz/en/>) from 2017 June to 2019 September, which crossed the IVZ along a west–east linear profile at 5 km interstation spacing. Overall, we processed seismic data from 61 broad-band seismic stations (Fig. S1 Supporting Information, for data availability plot versus time), centred on the IVZ and IvreaArray, providing a good ray path and azimuthal coverage (Fig. S2 Supporting Information).

The collected ambient noise data set was then partially reduced to account for one of the fundamental assumptions of seismic ANT: the isotropic distribution of noise sources (Lobkis & Weaver 2001). In fact, the isotropic distribution of noise sources is usually not satisfied within continental Europe during winter. Numerous studies

have shown that seismic noise in continental Europe is dominated by the surface waves generated in the Atlantic Ocean (e.g. Stehly *et al.* 2006; Yang & Ritzwoller 2008; Lu *et al.* 2018, among others), which significantly affects the spatial distribution of the noise sources in the period band of interest here (4–25 s). The analysis of the European seismic noise field suggests that seismic noise below 20 s period can be considered as isotropic during summer, rather than winter time (e.g. Yang & Ritzwoller 2008; Kvapil *et al.* 2021), which was also observed on a test subset of our database. Therefore, following the approach of, for example, Kvapil *et al.* (2021) and Pedersen *et al.* (2023), we restricted our data selection to the summer months of June, July and August. We ultimately obtained ambient noise data for 1830 station pairs. Most of the stations provided simultaneous recordings for up to three sets of summer data (2017–2019 June–August) except for CIFALPS I stations, which operated for *ca.* 14 months until 2013 September (Zhao *et al.* 2016). Permanent stations provided summertime data both for the year 2013, and from the year 2017 to 2019, which coincides with the time span of the CIFALPS I and the IvreaArray temporary passive seismic experiments respectively. Interstation distances range from 5 to 240 km.

3 METHOD

We invert surface wave velocity dispersion curves, derived from ambient noise data recorded simultaneously at various seismic stations, to obtain the distribution of v_S in the subsurface. This class of methods has proven to be effective from local (e.g. Lehujeur *et al.* 2018; Schippkus *et al.* 2020; Qorbani *et al.* 2022) to regional (e.g. Molinari *et al.* 2015b; Kästle *et al.* 2018; Kvapil *et al.* 2021) and global scales (Nishida *et al.* 2009; Schimmel *et al.* 2011). In general, the propagation of surface seismic waves is dispersive: as a function of their period, they sample different depth ranges in the crust and uppermost mantle, and thus they are sensitive to the respective velocities at depth. By quantifying this dispersion across a range of periods, the variation of v_S in the subsurface can be reconstructed. In the ANT framework, we measure the surface wave dispersion properties without relying on any signal from earthquake sources (e.g. Levshin & Ritzwoller 2001; Lobkis & Weaver 2001; Shapiro & Campillo 2004).

We processed the vertical component of the recorded ground motion to measure and invert the dispersion curves of the fundamental mode of Rayleigh waves (group velocities) in order to obtain a 3-D isotropic v_S model of the crust. Inverting phase velocity dispersion curves can provide useful complementary information as well. However, most methods for measuring phase velocity dispersion curves provide non-unique solutions (e.g. Ekström *et al.* 2009, among others). This non-uniqueness is usually addressed by considering realistic reference velocity values for v_S or a known relationship between phase and group velocities. However, the complex and heterogeneous study area (IVZ, Fig. 1) features lower-to-middle crustal rocks at shallow depths, next to upper crustal units and major sedimentary basins (e.g. Po plain—Molinari *et al.* 2015a). The choice of reference values for v_S would be subjective and prone to user interpretation error. Hence, we chose to analyse group velocities in this framework. The addition of phase velocity inversion, as well as Love waves inversion, will be proposed in subsequent studies.

The taken steps include: preliminary data processing; station-pair cross-correlation (CC) and stacking; frequency–time dispersion analysis (FTAN); periodwise computation of 2-D surface group-velocity maps and inversion of the 2-D maps for local 1-D velocity profiles, which, juxtaposed together, form the final 3-D model across the study area. These steps are presented below.

Following Bensen *et al.* (2007), we homogeneously pre-processed the raw data to enhance the ambient noise against other types of signal. We remove instrument response, bandpass-filtered the data in the 0.2–100 s period range (i.e. 0.01–5 Hz) and resampled the traces at 10 samples per second. To minimize the effect of coherent signals from local earthquake events without losing dispersion information, we performed amplitude normalization: each data point has been normalized by the mean amplitude of the selected moving window (Bensen *et al.* 2007).

The pre-processed data set was used to compute CC traces for each station pair. We used the MSNoise software package, from Lecocq *et al.* (2014), to store the seismic ambient noise data based on network, station, simultaneous recording time, to perform spectral whitening and to compute station-pairwise CC traces accordingly. For the CC task, we have split all the pre-processed waveforms in 1-hr segments with 50 per cent overlap and used a maximum CC lag time of 480 s. This maximum lag time, together with a maximum interstation distance of 200 km, ensured that we could measure low surface wave velocities (down to 1 km s⁻¹), which are expected for sediments in the Po plain in the south-eastern part of our study

area (Molinari *et al.* 2015a). Finally, the cross-correlated hourly traces were stacked to obtain one CC trace for each station pair (see Fig. S3 Supporting Information, for CC examples as a function of station-pair distance and for different period ranges of interest).

We applied FTAN (Levshin & Ritzwoller 2001) to measure the dispersion of the Rayleigh wave fundamental mode group velocities. This analysis provides average dispersion information along each station-pair path. To perform this, we used the empirical approximations of the group Green's functions (EGFs), computed from the processed ambient noise data; the EGFs were obtained by taking the average of the causal and acausal sides of each CC trace, and by computing the time derivative (with reversed sign) of the associated envelope (Lin *et al.* 2008). We still observed some amount of asymmetry in the causal and acausal portions of the EGFs, in the 5 to < 20 s period range. A similar asymmetry was also observed across other EGFs from ambient noise data collected in Europe (e.g. Yang & Ritzwoller 2008; Lu *et al.* 2018, among others). We argue that this is due to the directionality of the noise sources, which we addressed as much as possible by performing our analysis in the summer season.

In the FTAN, we filtered the obtained EGFs in narrow-frequency bands in the period range from 25 s down to 2 s, using a scaling factor of 1.4 to define each frequency band with respect to its central frequency f_0 (i.e. $[\frac{f_0}{1.4}, f_0 \cdot 1.4]$), and measured the group velocities for each period and station pair. We automated the measurement of group-velocity dispersion curves starting from a minimum period of 2 s where available. The maximum period of investigation was determined by the associated wavelength, which was required not to be longer than half the interstation distance, for each station pair (following e.g. Lin *et al.* 2008; Boschi *et al.* 2013, among others). Moving from longer to shorter periods, the automated picking process stopped either when the signal became too weak, that is, signal-to-noise ratio (SNR) lower than 5, or when picking became ambiguous because of several branches and local peaks in the diagram (Figs 2a–c). We manually re-inspected all the picks and finally stored dispersion curves for 1186 station pairs.

The measurement example for three station pairs in in Fig. 2 shows that including the IvreaArray seismic stations did provide higher resolution constraints across the study area—in particular, when mapping the transition from the slower Po plain area to the faster crustal structures in the IVZ (Figs 2b and c), and when mapping the transition from the IVZ to the northwest across the collision boundary (Figs 2a and c).

Next, we computed 2-D surface group-velocity maps in the 4–25 s period range (most complete range of measurements across the study area), using the Fast Marching Surface Tomography package (FMST, Rawlinson 2005). FMST solves an inverse problem to map the measured station-pair group velocities onto a regular grid, producing 2-D surface group-velocity maps. Based on our seismic station distribution, we set the horizontal grid spacing at 10 km by 10 km across the study area (e.g. Fig. 3, see Fig. S4 Supporting Information, for 2-D maps at selected periods). For each period, we performed a seven-iteration inversion starting from a constant 2-D velocity field of 2.5 km s⁻¹. Assembling the obtained 2-D maps provided local Rayleigh dispersion information, allowing extraction of local dispersion curves, one for each point of the final model grid (Fig. 3). Following the approach of previous authors (e.g. Mordret *et al.* 2015; Sánchez-Pastor *et al.* 2021), we estimated the effect of topography on our ambient noise dispersion measurements. We evaluated the change in interstation distances,

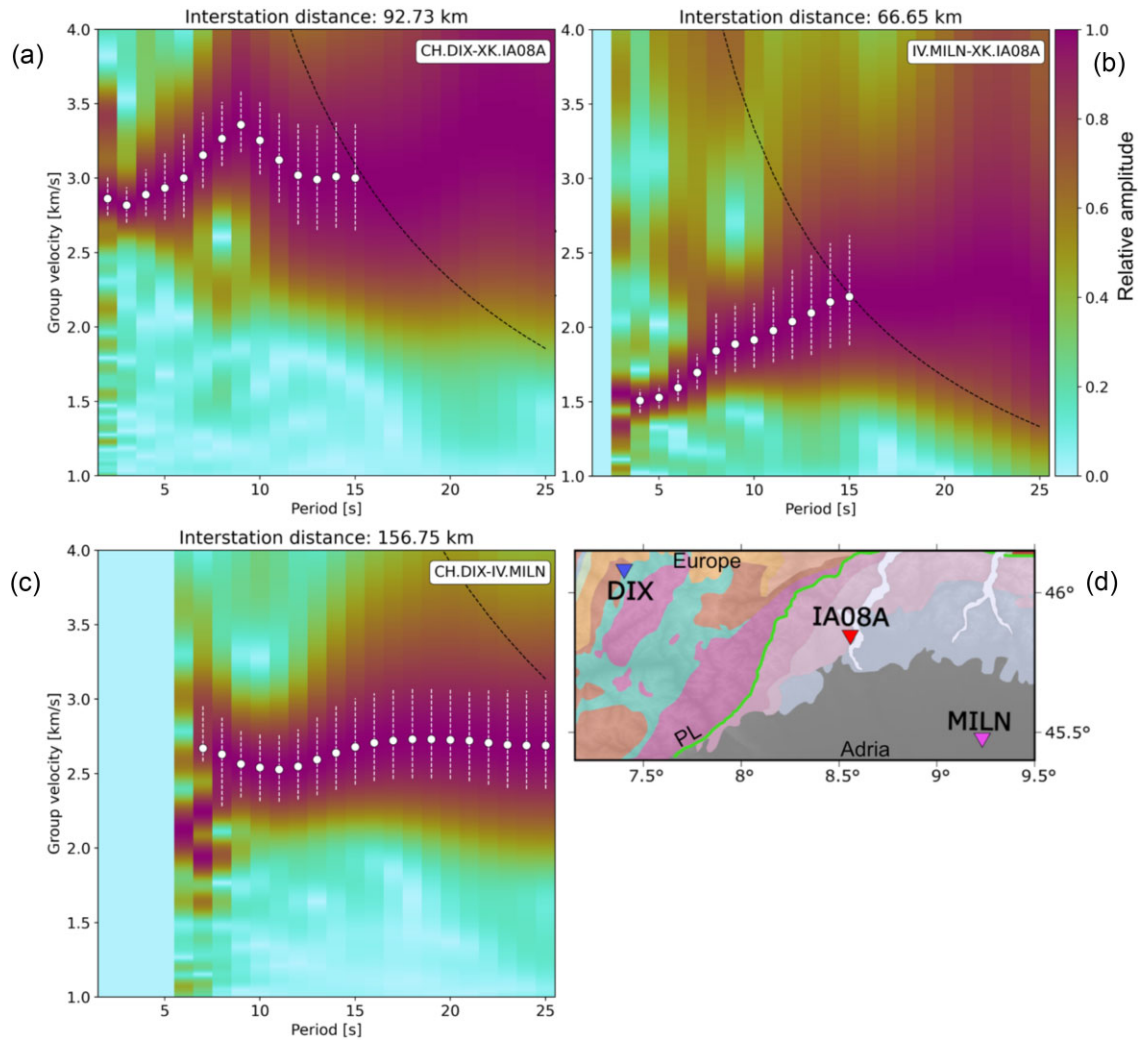


Figure 2. FTAN (Levshin & Ritzwoller 2001) used to measure the dispersion curves of Rayleigh waves group velocity from seismic ambient noise. The two-station analysis is here shown for three pairs of stations (see locations in d): (a) DIX and IA08A (dispersion curve with a local maximum at 10 s), (b) IA08A and MILN (monotonously increasing dispersion curve) and (c) DIX and MILN (dispersion curve with a local minimum at 10 s). The white dots indicate the measured group velocities at each period and the thin vertical bars indicate the group envelope width at 80 per cent of its maximum for uncertainty estimation (see Section 4). The thin black curve indicates the region in which the group-velocity assessment is not performed due to too short interstation distances.

with and without station elevation differences, for IvreaArray stations. In particular, IvreaArray presents the smallest interstation distances within our database, spanning from 777 to 250 m altitude, at the transition between Po plain and the pre-alpine area. As interstation distance variation is less than 1 per cent, we regard its effect as negligible for our application. As a final step, we inverted the local dispersion curves for 1-D v_S profiles by means of the stochastic neighbourhood algorithm (NA) via Dinver software (Wathelet 2008). We parametrized the 1-D v_S profiles as six horizontal, variable-thickness layers over a half-space, with each layer being associated with a velocity gradient implemented by five sublayers of constant velocity. We did not impose any further constraints on the velocity variation across the layer interfaces, allowing also discontinuous velocity changes with depth, as they could not be excluded *a priori* (see Fig. S5 Supporting Information, for inversion tests with increasingly tighter constraints on v_S , along the IvreaArray profile). We chose six layers to possibly account for shallow sediments, upper, middle and lower crustal structures, and eventually two uppermost mantle layers above the homogeneous half-space.

The Moho map from Spada *et al.* (2013) documents a significant jump across the Europe–Adria tectonic boundary, though partially unresolved, and presents spatially smooth interfaces elsewhere in the study area. Hence, we decided to invert the data without additional *a priori* constraints and we assigned an initial Moho depth of 30 km, allowing up to 20 per cent depth variation for each interface during the inversion. We used the Moho map from Spada *et al.* (2013) for later comparison with our results. Eventually, we performed a test inversion *a priori* including the available Moho model of Spada *et al.* (2013), obtaining consistent results with the final ones.

We point out that NA performs a statistical search across the model space (i.e. the ensemble of all the candidate crustal models for our problem), and provides the solution as an ensemble of statistically relevant models (Sambridge 1999; Sambridge & Mosegaard 2002). Consequently, we do not provide a single starting model for the inversion, but rather the allowed value ranges for all of the model parameters, shown in Table 1.

In particular, the NA stochastic exploration of the model space is guided based on two inversion parameters: number of initial models (n_0) and number of newly generated models at each iteration (n_r). For

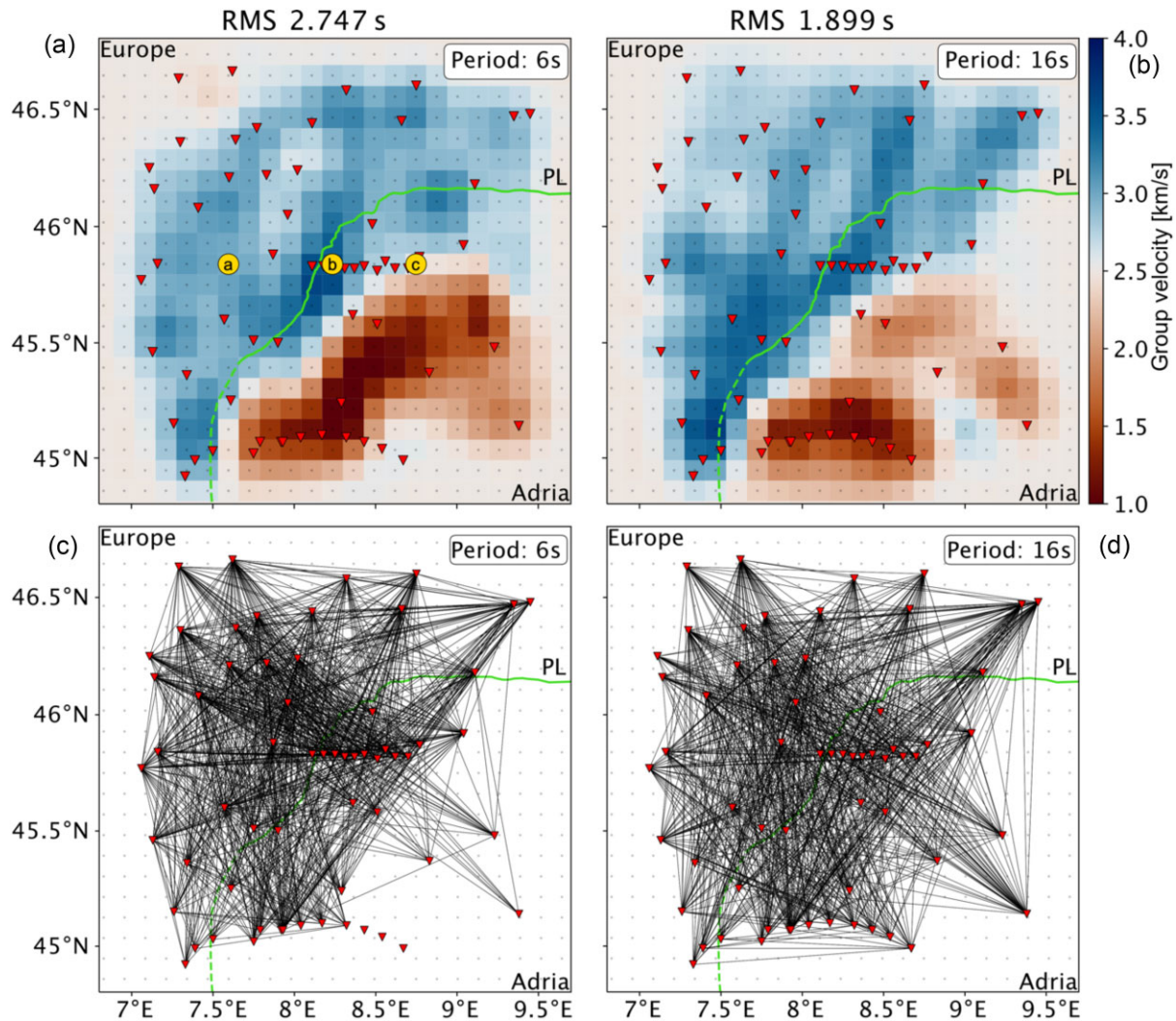


Figure 3. (a) and (b) Examples of 2-D group-velocity maps from the FMST method (Rawlinson 2005) selected at 6 and 16 s periods, chosen from the 4 to 25 s range analysed in this work. The three yellow circles in panel (a) show the locations of the 1-D profiles in Fig. 4. (c) and (d) Ray coverage for the dispersion measurements obtained at 6 and 16 s. The PL in green and the seismic stations as red triangles are shown for reference. Grey dots indicate the 10 km by 10 km gridpoints where the 2-D velocity maps were retrieved.

Table 1. Summary of the parameters and their ranges used in the stochastic NA inversion (Wathelet 2008), to obtain 1-D v_S velocity profiles from local group dispersion measurements.

Layer	v_S (km s^{-1})	Bottom depth (km)	v_P (km s^{-1})	Density (kg m^{-3})	Poisson's ratio	Number of sublayers	Structure change
Near surface	1.2–4.3	0.1–9	3.3–5.5	2.0–3.5	0.2–0.5	5	Positive linear gradient
Upper crust	2.5–4.3	12–18	5.0–7.0	2.7–3.5	0.2–0.5	5	Linear gradient
Middle crust	3.0–4.3	18–27	5.0–7.0	2.7–3.5	0.2–0.5	5	Linear gradient
Lower crust	3.0–4.3	24–36	6.5–8.0	2.9–3.5	0.2–0.5	5	Linear gradient
Uppermost mantle 1	3.0–4.5	47–53	7.0–8.5	3.1–3.5	0.2–0.5	5	Linear gradient
Uppermost mantle 2	3.0–4.9	70	7.0–9.0	3.1–3.5	0.2–0.5	5	Linear gradient
Half space	3.0–5.0	–	7.0–9.0	3.1–3.5	0.2–0.5	–	None (homogeneous)

each inversion, we used 500 starting models, and 200 new models generated for each of 300 iterations; in total, we tested 60 500 1-D v_S models at each gridpoint. Finally, we defined the local 1-D velocity profiles as the average of the 10 per cent (i.e. 6050) best-performing models.

4 UNCERTAINTY, RESOLUTION AND SENSITIVITY

We discuss the main sources of uncertainty and how they were identified and treated within our multistep inversion process. For

the sake of the uncertainty estimation of traveltime measurements from EGFs, and for consistency with respect to the FTAN analysis and the FMST software, in this section we discuss *group traveltime* measured between two stations instead of *group velocity*: for a given period and a given station pair, the measured *group velocity* equals the interstation distance over measured *traveltime* (i.e. $v_{\text{meas}} = d/t_{\text{meas}}$). The traveltime uncertainties were then used as input in the FMST package, for the computation of 2-D surface group-velocity maps.

For this reason, we designed a procedure to evaluate the uncertainties on traveltime measurements, based on the EGFs peak width's distribution across all the station pairs. In particular, we measured the group envelope widths at 80 per cent of the envelope's maximum amplitude for each period of interest: the wider the peak with respect to the period mean, the higher the uncertainty (see the white dashed segments in Figs 2a–c, e.g. of peak width measurements, and Fig. S6, Supporting Information, for peak width distributions at selected periods). First, we attributed a minimum uncertainty of 0.1 s to the traveltime measurements. Then, we linearly increased the uncertainty to 0.5 s, for those arrivals whose width was between 1 and 2 standard deviations (STD) higher than the mean. Finally, we linearly increased the uncertainty from 0.5 to 2 s for those, whose width was between 2 and 3 STDs higher than the mean; and kept 2 s beyond. Within FMST, 0.5 s uncertainty resulted in a smaller input weight and 2 s uncertainty makes the traveltime datum negligible for the sake of the 2-D inversion. We compared our uncertainty estimates to those obtained by recomputing the EGFs with random subsets of daily CC traces (ca. 30 per cent of the database for one test station pair), and obtained consistent results. We consider that our procedure provides a rather conservative uncertainty estimate.

Subsequently, we performed resolution tests for the computation of the 2-D surface velocity maps, to estimate the spatial scales and velocity anomalies we could constrain given our data coverage. We inverted synthetic traveltimes, generated for a random 2-D surface velocity distribution (following e.g. Verbeke *et al.* 2012; Molinari *et al.* 2015b), ranging from 1.5 to 4 km s⁻¹. Prior to the synthetic test, we added random Gaussian noise (with 0.1 s mean and 0.1 s STD) to the synthetic observations (see Fig. S7 Supporting Information, for resolution tests at selected periods).

We also performed extensive testing to find a combination of smoothing and damping parameters which (1) did not provide any single cell velocity perturbations; (2) did not provide velocity perturbations beyond the 1–4 km s⁻¹ boundaries and (3) did not provide velocity patterns correlated with the ray path distribution at any period (see Fig. S8 Supporting Information, for an example of root-mean-square RMS error, model variance and model roughness variation as a function of smoothing and damping parameter values). Finally, we identified 20 km (i.e. two grid cells size) as the minimum length-scale we could resolve, in particular at upper crustal depths where the resolution at the shortest periods we employed is the highest (Figs 4g–i).

Concerning the NA inversion, the sensitivity kernels computed for the final 1-D v_S velocity models for our period range of interest (4–25 s), show a decrease in sensitivity for v_S at ca. 30–35 km depth (Figs 4g–i). While the sensitivity does not decay to zero (Figs 4g–i), the upper and middle crustal depths remain the best resolved areas for the period range used in this work. Typical lower crustal depths represent the lower limit of our depth resolution. While we observe a Moho-related velocity increase, which is smoother on the European side than the Adriatic counterpart (Figs 4d–f), this suggests not to interpret additional velocity features below the Moho discontinuity across our study area.

Eventually, we infer the Moho-related velocity gradient at 30–50 km depths depending on the location.

Concerning the final 1-D v_S profiles obtained from the NA inversion, we obtained a maximum 0.15 km s⁻¹ STD of v_S values within the best 10 per cent performing models, and we regard this as a suitable estimate for the uncertainty on the final v_S velocity values.

5 RESULTS

We built the final 3-D v_S model underlying the IVZ by juxtaposing the local 1-D velocity profiles, which were obtained in the NA inversion at each model gridpoint. We applied nearest point interpolation and a Gaussian filter with a 5 km length-scale to produce vertical cross-sections of the model. The 3-D model provides a satisfactory fit of the dispersion data across the sampled volume (e.g. Figs 4a–c) and presents first-order variations in the velocity structure across the different tectonic domains in our study area.

We can pinpoint these structural differences by looking at the different v_S profiles reported in Figs 4(d)–(f). Each of them is located in a different tectonic domain: European, IGB and Adriatic, respectively. Both the European and the Adriatic domains (Figs 4d and f) present a local velocity structure with a positive gradient from the surface down to ca. 12–16 km depth. We observe a slower crustal v_S structure on the European side than on its Adriatic counterpart (Fig. 4f), extending from ca. 20 to 35 km depth (Fig. 4d). Both the European and the Adriatic profiles show a sharp velocity increase associated with the Moho discontinuity, where v_S reaches 4 km s⁻¹, though at different depths: ca. 30 km depth on the Adriatic side (Fig. 4f) and ca. 50 km depth on the European side (Fig. 4d).

Strikingly different from the previous two zones, the structure associated with the IGB anomaly presents higher velocities at shallower depths (Fig. 4e): v_S exceeds 3.6 km s⁻¹ at the surface and the shallowest crustal layer, and reaches more than 4 km s⁻¹ at ca. 25–30 km depths.

Horizontal slices through the model reveal that the velocity distribution correlates well in space with geological units mapped at the surface and the main tectonic structures in the same area, and points at some new features (Fig. 5). At depths from 2 to 10 km we identify the dominant contribution of the slow Po plain sediments, which is clearly visible to the southeast of the PL (Figs 5a–c), in contrast with the fast crustal structure on the northwestern side of the Insubric segment of the PL (Figs 5a–c).

Most importantly, we image a shallow and isolated high-velocity anomaly, prominently visible on the 2 and 5 km depth sections of the model at the centre of the study area (Figs 5a and b). The location of this shallow high-velocity anomaly corresponds well with the location of the IVZ lower-to-middle crustal and mantle peridotite outcrops exposed at the surface (Fig. 1). This high-velocity feature, located in correspondence of the two westernmost stations of the IvreaArray profile, and which we associate with the shallow-lying IGB in the IVZ (see discussion in Section 6), becomes elongated and continuous along the PL at 10 km depth (Fig. 5c). This highlights that the velocity structure varies both with depth, and along the main tectonic boundary. At increasing depths from 2 to 10 km below the surface, the high-velocity IGB anomaly evolves from local in the IVZ (Fig. 5a) to elongated along the strike of the European–Adriatic collision (Fig. 5c). Deeper in the crust, the European side shows velocities slower than in Adria; however, this slower trend is located further to the north-west with respect to PL (Figs 5e and f).

To image the structure of the continental collision at depth and its variation along strike, we analyse velocity variations along

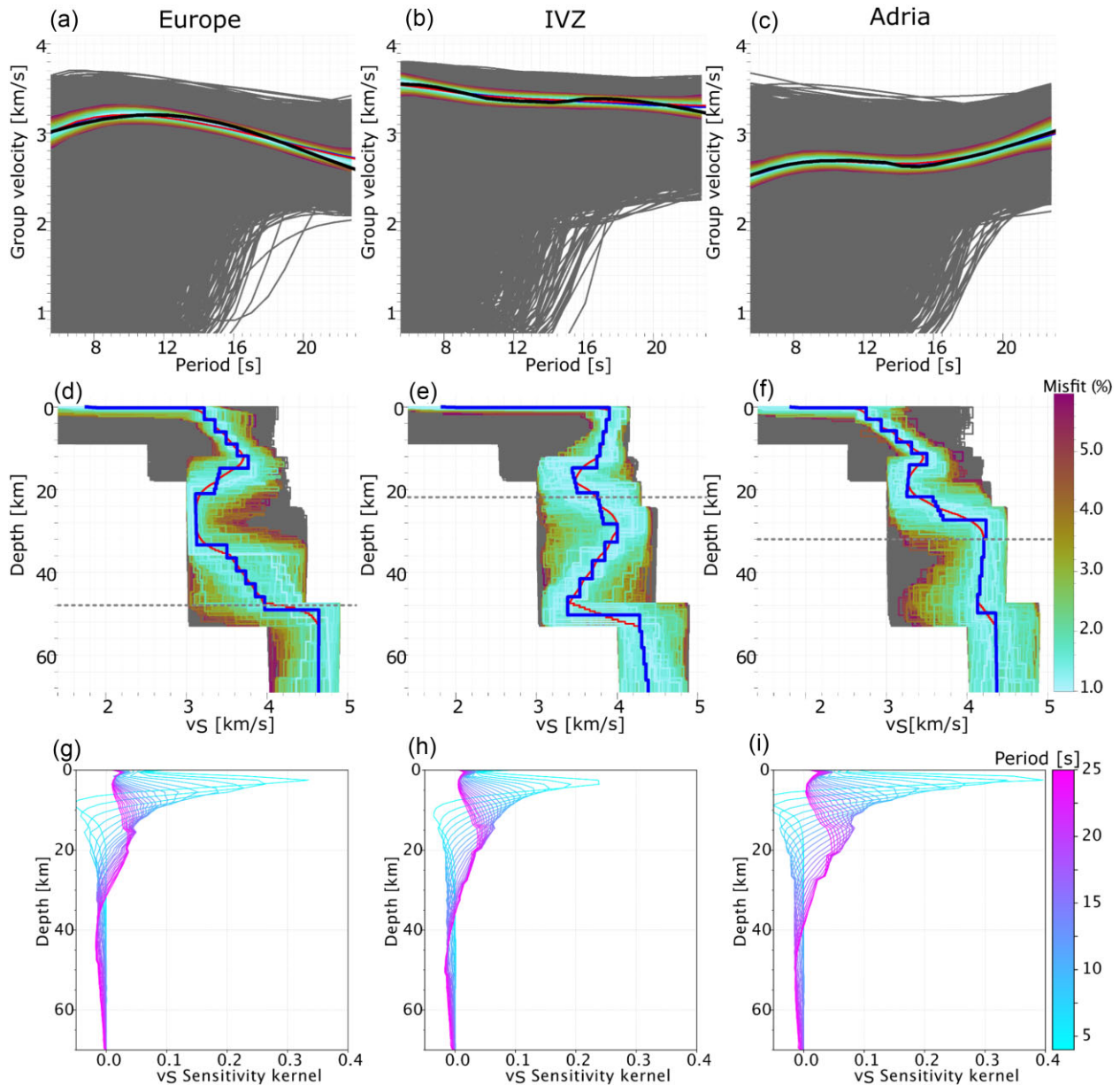


Figure 4. Examples of modelled dispersion curves at three different locations along the IvreaArray profile: Europe, IVZ, Adria (marked as locations *a*, *b* and *c* respectively in Fig. 3(a)). (a)–(c) The observed (black) dispersion curves are compared with synthetic ones: the layer-averaged (blue) and depth-averaged (red) models, respectively. Both layer and depth averages are computed based on the best 10 per cent performing models (shown in colour); the remaining models are shown in grey. (d)–(f) The corresponding 1-D v_S velocity models obtained from the inversion with the improved stochastic NA (Wathelet 2008): the layer-averaged (blue, used for the final 3-D model) and depth-averaged (red) models. The best 10 per cent models are shown in colour, the remaining ones in grey. The local Moho depth from Spada *et al.* (2013) is shown for reference (grey dashed line). (g)–(i) Group-velocity sensitivity kernels for the fundamental mode of Rayleigh waves for v_S from period 4 s (cyan) to 25 s (magenta).

several vertical cross-sections through the model (Fig. 6). A pronounced and shallow high-velocity anomaly is observed beneath the IVZ along profile P2, which corresponds to the IGB (Fig. 6a), and reaches the surface at the location of the lower crustal and Balmuccia mantle-peridotite outcrops. High-velocity features at upper crustal levels are also visible along profiles P1 and P3, crossing the southern and the northern parts of the IVZ, respectively (Figs 6b and c), though without reaching the surface as in profile P2, but culminating rather at 10–15 km depth, respectively. Despite the overall v_S sensitivity decrease at

ca. 30–35 km depth (Figs 4g–i), we identify a major velocity increase along all the profiles P1, P2 and P3, which correlates well with the previous Moho discontinuity mapped by Spada *et al.* (2013—Figs 6a–c), with a sharper and better matching gradient on the Adria side, in particular.

6 DISCUSSION

Performing ANT with the IvreaArray seismic data provides new results on the geometry and the physical properties of the shallow

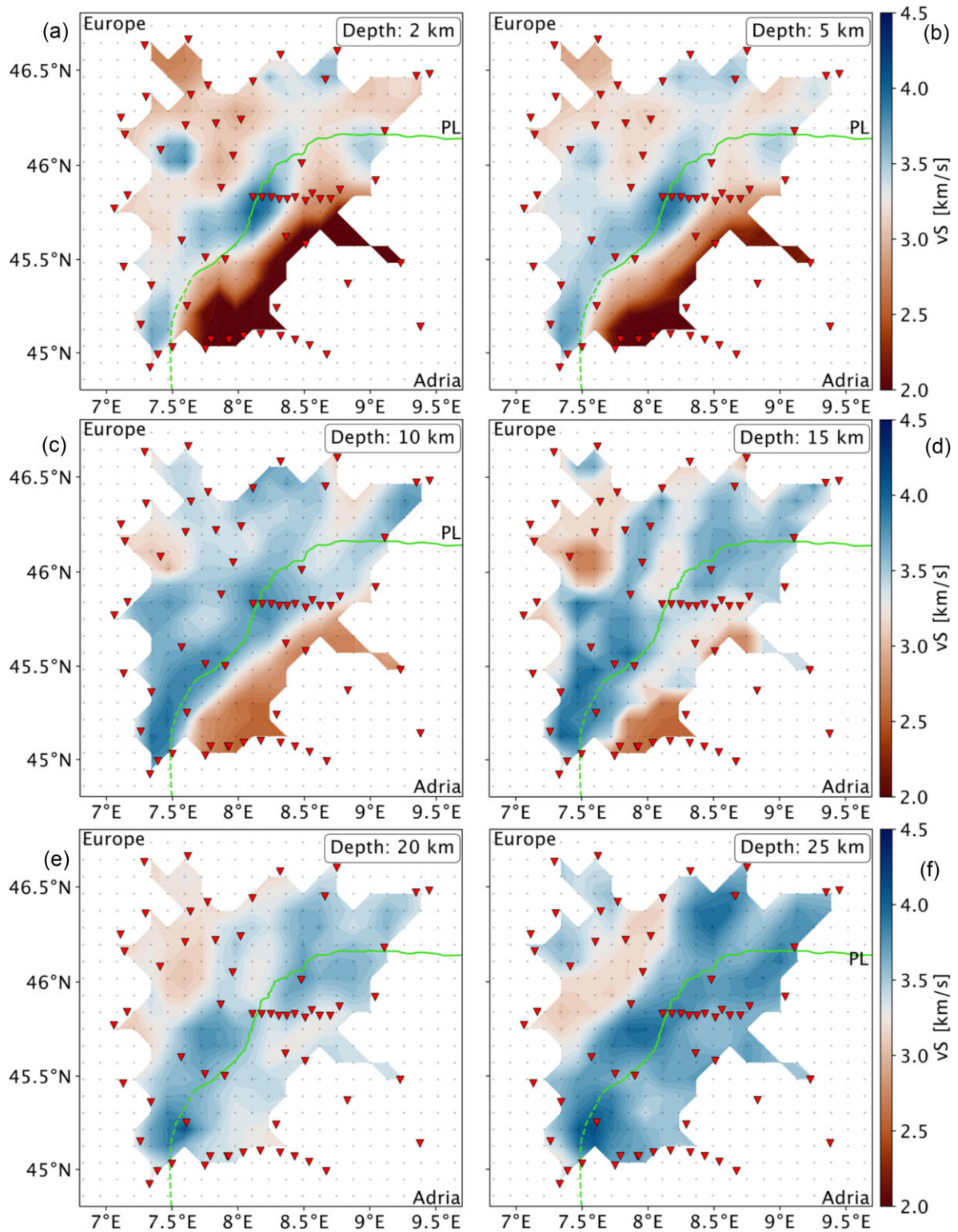


Figure 5. (a)–(f) Horizontal slices through the final 3-D v_S model at different depths. The 1-D depth inversion was performed for each gridpoint, which counted at least at 10 rays, and the resulting 1-D models were combined to the final 3-D model shown in this figure. The PL and the seismic stations are shown for reference.

crust and of the IGB structure. These results can be interpreted in comparison with previous geophysical investigations in the same area, and the geological observations at the IVZ surface.

For this purpose, the east–west oriented IvreaArray profile represents a key transect, along which we can compare the present results

directly with the recent RF and gravity studies (Scarponi *et al.* 2020, 2021). At the centre of this profile, our v_S model clearly maps a distinct high-velocity anomaly at the Europe–Adria collision boundary (8.2° longitude), extending from the surface down to *ca.* 10–12 km depth. We interpret it as the fastest and shallowest portion of the

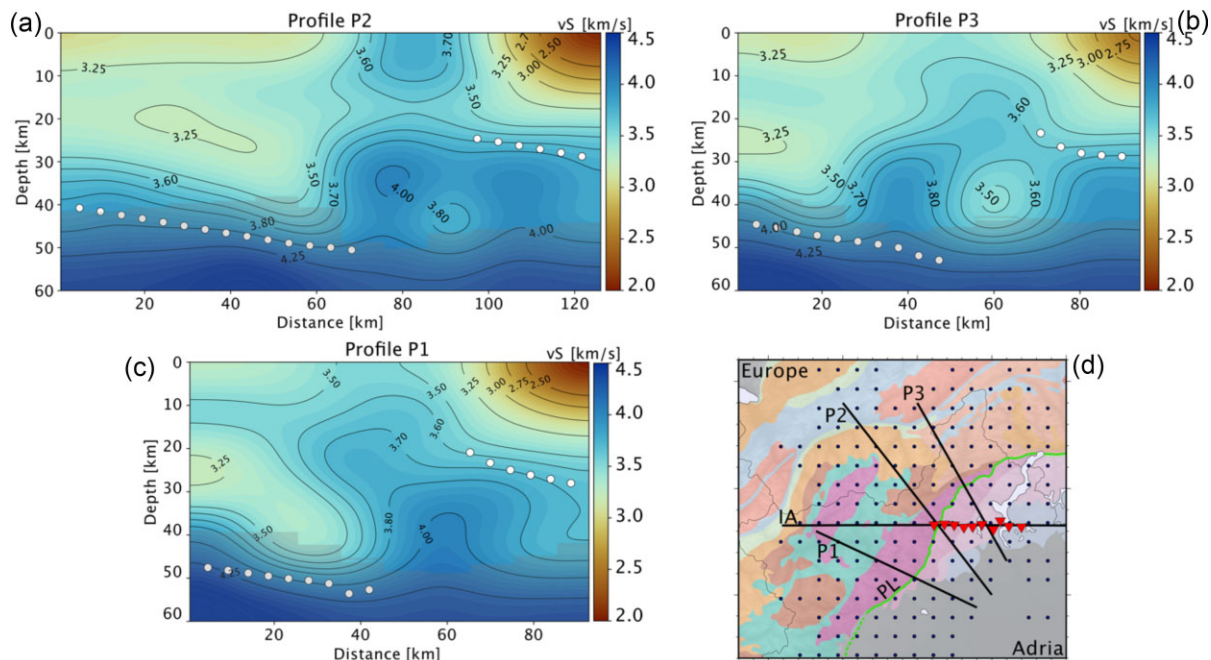


Figure 6. (a)–(c) Vertical cross-sections of the 3-D v_S model along three profiles P1, P2 and P3. The white dots show an interpolation of the Moho map from Spada *et al.* (2013) along the considered profiles. Grey-shaded areas indicate parts of the model, where the sensitivity kernels have amplitudes lower than 5 per cent of their maximum, across all the periods of interest. (d) The location of the three profiles (P1, P2 and P3), together with the IvreaArray seismic stations and the map from Fig. 1 for reference. The profile IA is shown in Fig. 7. The black dots are the gridpoints where the NA inversion for the 1-D v_S velocity profiles was performed.

IGB, reaching the surface within our resolution capabilities, and presenting v_S values up to 3.8 km s^{-1} at subsurface—up to 0 km to few km depths (Figs 7a).

To our knowledge, this is the first evidence of a shallow-lying IGB beneath the IVZ mantle and lower crustal outcrops, from v_S tomography.

The resolved high v_S anomaly correlates well with the shallowest portion of the 3-D IGB density model along the same profile (Fig. 7a), the latter obtained by previous independent gravity anomaly modelling (Scarponi *et al.* 2020).

The ANT results also agree with the independent 2-D RF migration analysis based on P -to- S conversions (Scarponi *et al.* 2021; Fig. 7b). The RF migration image shown in Fig. 7(b) should be interpreted as follows: positive (green) amplitudes represent an increase of seismic velocity with increasing depth, while negative (blue) amplitudes a decrease. RFs are useful in mapping the sharp contours of bulk velocity anomalies. In this case, the RF migration image shows a sharp increase in seismic velocity at the top of the IGB, which corresponds well with the shallow high-velocity anomaly mapped by ANT (red boxes, Fig. 7b). A good agreement is also observed on the Adriatic side further to the east, in correspondence of the Moho-related positive velocity gradient (red boxes, Fig. 7b).

However, such shallow, sharp velocity discontinuities can produce multiple reflections, which may mask later signals in the RFs, making deeper features less reliable for interpretation (pink and white boxes, Fig. 7b). This could be the case for the negative RF signal mapped in correspondence of an ANT low-velocity feature at *ca.* 40 km depth (white box, Fig. 7b), which presents good agreement in terms of location among the two methods. This slower feature is also visible further to the north along profile P3, and partially along profile P2 (Figs 6a and b). Along the IvreaArray profile, this is mapped only on one model gridpoint by ANT, and we do

not regard it as well resolved. If real, it could point towards v_S heterogeneities within the IGB at lower crustal depths, and warrants attention in future local investigations.

Our new results are also consistent with the best-performing model geometries from the 2-D joint RF and gravity inversion. There, the shallowest geometries reach 3–7 km depths in correspondence with the high-velocity feature resolved by ANT in this work (Fig. 7c, Scarponi *et al.* 2021). The agreement between the results of these two independent methods continues down to 30–40 km depths, where the modelled vertical structure bounds the high-velocity IGB in the crust.

In terms of large-scale structures, we observe consistent results in the European and Adriatic tectonic domains, with respect to the Moho mapped by Spada *et al.* (2013—Fig. 7a), the latter presenting a gap where we resolve the shallowest IGB portion at higher resolution. At the centre of the IVZ and perpendicular to the strike of the collision, the velocity contrast between the European and the IGB domains appears to be sharp throughout the whole crust (Fig. 6a), with systematically higher velocities on the Ivrea side (Figs 6a–c). A lower velocity structure west of the Ivrea body was also observed by Solarino *et al.* (1997) along the NW-SE ECORS-CROP transect further to south, and interpreted as the suture zone between the European and the Adriatic plates (Schmid & Kissling 2000). In our model, a slower European lower crust is visible throughout the whole study area, juxtaposed to the IGB high-velocity anomaly (Figs 6a–c).

We compare our model with the local earthquake tomography (LET) by Diehl *et al.* (2009). The LET approach results in a 3-D P -wave velocity model for the lithosphere, by simultaneously inverting for the hypocentres of local earthquakes and the surrounding 3-D velocity structure. In the case of Diehl *et al.* (2009), a new 3-D v_P model is derived. We refer to their work for further details

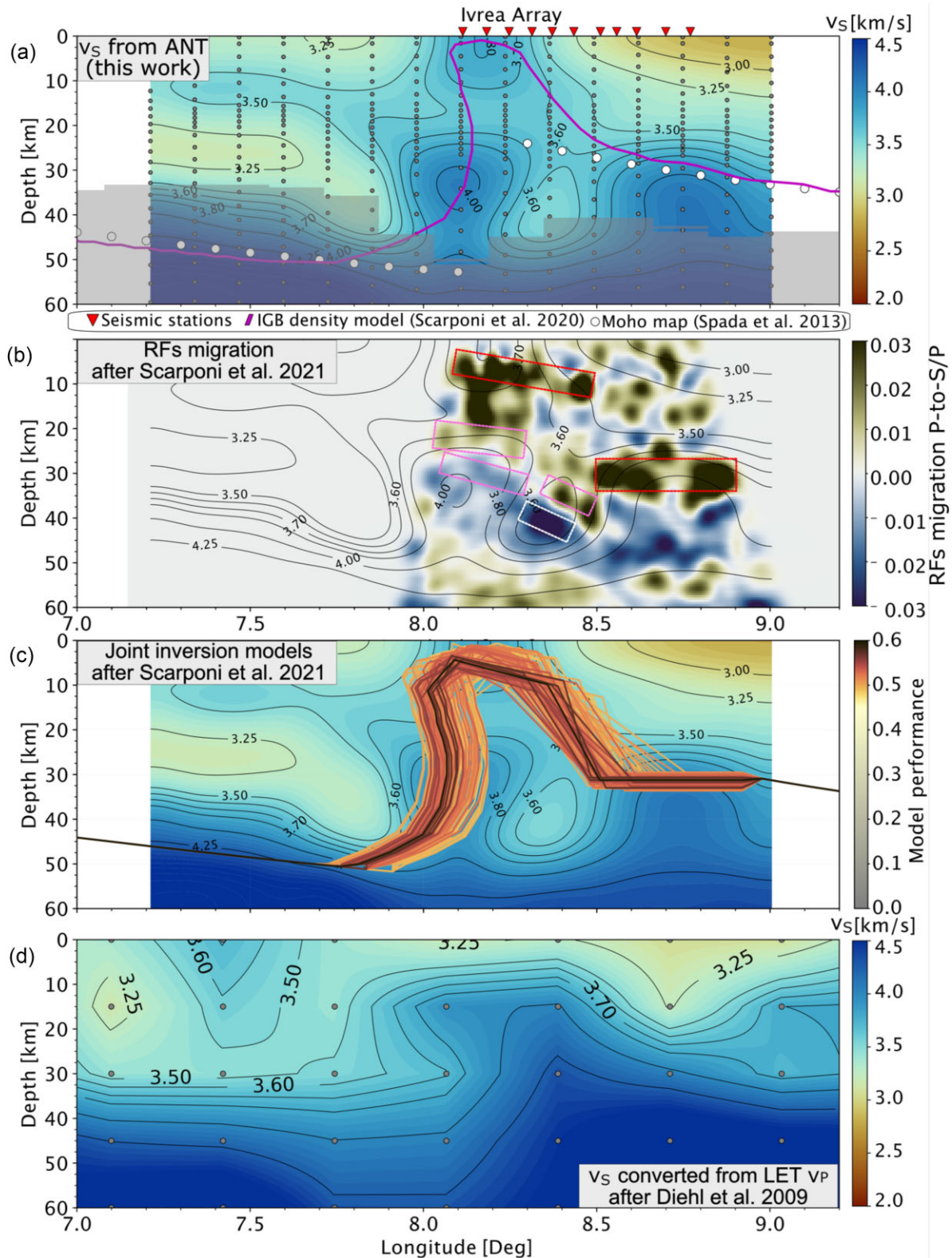


Figure 7. Comparison of various geophysical investigations and models along the west-east IvreaArray 'IA' profile (location in Fig. 6d). (a) Vertical cross-section of the 3-D v_s model obtained in this study. White dots represent Moho depth from Spada *et al.* (2013), red triangles on top indicate the location of the IvreaArray seismic stations. Magenta contour represents the main density jump in cross-section of the 3-D IGB density model from gravimetry by Scarponi *et al.* (2020). Grey dots indicate the model nodes used in the NA inversion for the 1-D v_s profiles. In the grey-shaded areas, sensitivity kernels have amplitudes lower than 5 per cent of their maximum, across all the periods of interest. (b) P -to- S converted RF migration image for the best-performing model in the joint RF-gravity inversion of Scarponi *et al.* (2021), along the same profile. Green and blue colours respectively indicate increase and decrease of v_s with depth. The v_s contours obtained in this study are overlaid. (c) 150 best model geometries from the joint RF-gravity inversion of Scarponi *et al.* (2021); the darker the colour, the better fit to the data. (d) Model cross-section from LET by Diehl *et al.* (2009), converted to v_s by using an average constant v_p/v_s ratio of 1.73.

on the LET methodology. Eventually, for the sake of a qualitative comparison between the LET model and our final 3-D v_S model, we converted the v_P model from Diehl *et al.* (2009) to a v_S model, by assuming a constant and average v_P/v_S value of 1.73 for our study area (Solarino *et al.* 2018; Colavitti *et al.* 2022). Most importantly, the LET work by Diehl *et al.* (2009) locates high velocities representing the shallowest IGB portion only up to ca. 10–12 km depth, not suggesting any connection to the surface, similarly to what was obtained further to the south from the temporary passive seismic experiments CICALPS I and CICALPS II (Solarino *et al.* 2018; Paul *et al.* 2022). While the lack of IGB-to-surface connection may stem from the model and/or data resolution in the case of Diehl *et al.* (2009, given at 25 km horizontally and 15 km vertically) and CICALPS II models, it could be a real feature in CICALPS I (south of the IVZ), where no lower-to-middle crustal composition outcrops are exposed at the surface (e.g. Schmid *et al.* 2004; Paul *et al.* 2022). However, a final analysis of the IGB-surface connection along the latter profiles (CICALPS I and II) requires locally higher resolution imaging.

Comparing with Diehl *et al.* (2009), we can also observe second-order structural differences in the seismically slower sediment area on the Adriatic side (most likely related to the Po plain area, Figs 7a and d) and also on the European side, where the Moho is generally deeper, and a relatively slower and deepening crustal structure is mapped by both methods.

Overall, and in comparison with previous tomographic works covering the same area (e.g. Diehl *et al.* 2009; Kästle *et al.* 2018; Lu *et al.* 2018; Solarino *et al.* 2018), we benefit from the additional coverage provided by the densely spaced IvreaArray stations' data (Fig. 2), which allowed us to image the shallow-lying connection between the IVZ lower-to-middle crustal rock outcrops and the IGB coming nearly abreast at an unprecedented resolution (Figs 7a and d).

While we also associate the high-velocity structure at ca. 30–40 km depth and 8.1° longitude with the IGB, the nature of the relatively lower velocity feature between 15 and 20 km depth and 8.2° longitude is less certain (Fig. 7a). Although it still presents a high velocity of 3.6 km s⁻¹ when compared to classical middle crustal depths, the 0.15 km s⁻¹ uncertainty on v_S does not allow a firm conclusion.

The newly obtained constraints on the shallow IGB's physical properties can be also compared with the physical properties of the rock samples, which were collected across the IVZ outcrops and analysed in the laboratory by previous authors (e.g. Khazanehdari *et al.* 2000; Zappone & Kissling 2021). While these values come from two very different spatial scales (1-to-10 km vs 1-to-10 cm), their comparison can help to rule out and/or to discuss some candidate rocks for the composition of the subsurface physical structure. Based on this work, we suggest a 3.6–4.1 km s⁻¹ v_S range (including uncertainties) for the IGB's shallow structure, beneath the IVZ outcrops (Fig. 7). In addition to this, previous 3-D and 2-D gravity modelling suggests a range of density values from ca. 2900 kg m⁻³ to a maximum of 3200–3300 kg m⁻³ for the same structure (Scarponi *et al.* 2020, 2021). These geophysical observations are compatible with the physical properties of some of the ultramafic rock samples collected in the IVZ and analysed in the laboratory, even though other ultramafic rock samples present higher v_S and higher density values (Fig. 8). Ultramafic rocks, in particular mantle peridotites, were previously suggested as the possible main components for the IGB by Scarponi *et al.* (2020). While this hypothesis remains valid in light of the new geophysical results, the new v_S constraints are also compatible with other lower crustal rock types, such as

amphibolite, stronalite and gabbroic rocks (Fig. 8). Amphibolite gabbros were also suggested by Pistone *et al.* (2020) as the most likely IGB components, based on petrophysical modelling of larger scale ρ - v_P geophysical observations. However, Pistone *et al.* (2020) had v_P constraints available from larger scales LET by Diehl *et al.* (2009) and no high-resolution v_S constraints (Lu *et al.* 2018; Kästle *et al.* 2018 provide much smoother models across the same area). It should also be noted that eclogite rocks may also contribute to the high-velocity anomaly associated with the IGB. Nevertheless, we do not suggest them as the main component of the IGB on the southern Alpine side of the continental collision, which should be rather dominated by high-temperature metamorphic rocks (Scarponi *et al.* 2020).

The comparison of rock properties across spatial scales should consider the effect of anisotropy, not only of the rock samples, but of passive geophysical methods, as for example RF samples mostly along vertically propagating rays, and ANT mostly along horizontally propagating signals.

Alder *et al.* (2021) and Kästle *et al.* (2022) have investigated azimuthal and radial v_S anisotropy at larger spatial scales, and the patterns they observe are not clearly interpretable within our model area. In this regard, future analysis is needed (i.e. including Love waves) to highlight the possible characteristics of anisotropy at intracrustal scales in the IVZ.

At a much smaller scale, Khazanehdari *et al.* (2000) measured up to 5 per cent positive anisotropy ($v_{SV} > v_{SH}$) for the lower crustal and mantle rocks sampled at the IVZ surface, which may contribute with a bias up to 0.2 km s⁻¹ in our comparison between laboratory analysis and geophysical results (Fig. 8). Ultimately, the analysis of rock samples from the DIVE drilling project will provide new information on the anisotropic properties of the rock lithologies in the IVZ area (Pistone *et al.* 2017), and will allow an additional comparison with the current geophysical results.

Further structural discussion of our results is warranted in light of the recent high-resolution traveltimes tomography, performed at km-scales across the Balmuccia mantle peridotite outcrop with new controlled-source seismic data (Ryberg *et al.* 2023). The v_P model by Ryberg *et al.* (2023) presents a continuous fast structure extending and broadening from the surface mantle peridotite outcrop down to maximum 3 km depth below sea level; this, together with our findings, suggests that the Balmuccia outcrop is likely the exposed portion of a protuberant body, and not only a surficial lens embedded in lower crustal rocks as referred to by Quick *et al.* (2003). Our results support the shallow, km-scale interpretation of Ryberg *et al.* (2023) and the possible existence of a mantle rock body continuously extending from the surface, producing a high-velocity anomaly within the whole upper crust. Based on our new 3-D v_S model, we corroborate the model for which the entire crust was tilted and brought up to the surface, without major internal deformation (e.g. Zingg *et al.* 1990).

This suggests that peridotites may contribute to the high-velocity anomaly we resolve in the IVZ. Hence, the IGB geophysical anomaly may consist of a combination of both mantle peridotite and lower crustal rocks, bound in a complex and heterogeneous structure, whose internal distribution lies at spatial scales below the resolution of ANT. Based on these, we provide a new structural interpretation of the IGB along a linear NW-SE reference profile, crossing the IVZ perpendicularly to the main strike of the Europe-Adria collision, and centred on the Balmuccia mantle peridotite outcrop (Fig. 9). The new v_S model and the surface geological observations together enable association of the base of the IGB with Adriatic mantle rocks, and its shallower portion with a heterogeneous

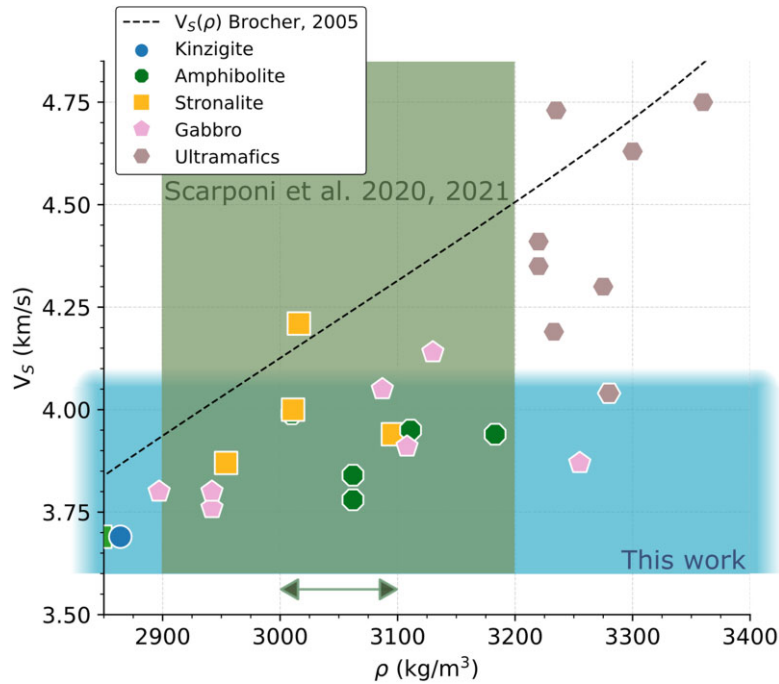


Figure 8. Comparing physical properties across scales, between the 1–10 cm size rock samples collected across the study area, and the constraints obtained from larger scale (> 10 km) passive geophysical studies. The green area represents constraints on density and v_S , obtained from previous joint seismology-gravimetry inversion (Scarponi *et al.* 2020, 2021). The blue area represents constraints on v_S only, as obtained from seismic ANT in this work. Both areas represent the physical properties of the shallow crustal geophysical anomaly associated with the IGB. As the gravity inversion constrains density contrasts and not absolute values, the green box can be rigidly translated along the x -axis by up to 100 kg m^{-3} . Finally, the scatter plot shows the rock physical property data from the SAPHYR catalogue (Zappone & Kissling 2021) for samples collected in the IVZ (Fig. 1). The black dashed line represents the v_S – ρ (velocity–density) relationship obtained by regression on laboratory data (Brocher 2005).

structure, featuring lower crustal and mantle rocks at shallow depths beneath the IVZ. At greater depth, the base of the IGB penetrates further to the west and neighbours the European lower crust in place with the largest Moho offset between the European and the Adriatic Mohos. The shape of this structure generally follows that resolved by the 3-D gravity modelling and the 2-D joint gravity-RF inversion. The crustal structure from surface sediments to Moho, bent and tilted towards the surface during the continental tectonic collision, now displays subhorizontal (instead of vertical) layering at the IVZ surface. Further to west of the IVZ, at depth, the structures must have been affected by the emplacement of the IGB and the deformation along the PL, but remain unresolvable with passive geophysical methods.

As the nature and the characteristics of a palaeo-Moho transition zone beneath the IVZ still constitute open targets under investigation, the ongoing scientific drilling project DIVE may provide unprecedented information on physical properties across a range of scales (Pistone *et al.* 2017—<http://www.dive2ivrea.org/>). In particular, DIVE-phase II aims at performing a 4-km-deep drilling in the Balmuccia peridotite area, enabling a direct comparison with the current geophysical results in the near future and further advancing our understanding of the IGB and the continental lower crust.

7 CONCLUSIONS

We present a new 3-D shear wave seismic velocity model for the crust in the IVZ, derived from ANT, via an NA algorithm inversion of Rayleigh group-velocity dispersion curves (fundamental mode).

We achieved higher resolution at crustal depths (i.e. minimum horizontal length-scale of 20 km) with respect to previous tomographic works targeting the Western Alps, by processing ambient noise data from both permanent and temporary seismic stations, in addition to the seismic data from the temporary IvreaArray network; the latter designed to locally investigate the IVZ subsurface.

The new detailed image of the IGB anomaly in the IVZ shows a unique structure and physical properties with respect to the neighbouring European and Adriatic domains. The physical structure associated with the IGB presents a shear wave seismic velocity of at least 3.6 km s^{-1} directly from the surface, increasing up to 4 km s^{-1} at 20–25 km depth. This shallow fast-velocity anomaly, within our resolution, reaches the surface in remarkable agreement with the location of the lower-to-middle crustal composition rocks and the Balmuccia peridotite exposed in the IVZ. This suggests a likely continuity between the surface geological observations and the subsurface geophysical anomalies.

Furthermore, the analysis of both vertical and horizontal cross-sections of the model indicates important variations in the IGB structure along the continental collision boundary. While the high-velocity IGB anomaly reaches its shallowest depth (surface) in the Balmuccia area, the related anomaly extends up to 10 and 15 km depth beneath the southern and northern edges of the IVZ respectively, similarly to the findings of other tomographic studies in the southwest of IvreaArray (CIFALPS I and CIFALPS II experiments, e.g. Solarino *et al.* 2018; Paul *et al.* 2022). The comparison with the results from both the joint and separate RFs and gravity-anomaly modelling (Scarponi *et al.* 2020, 2021) further supports the interpretation of a very shallow reaching (and possibly outcropping) IGB

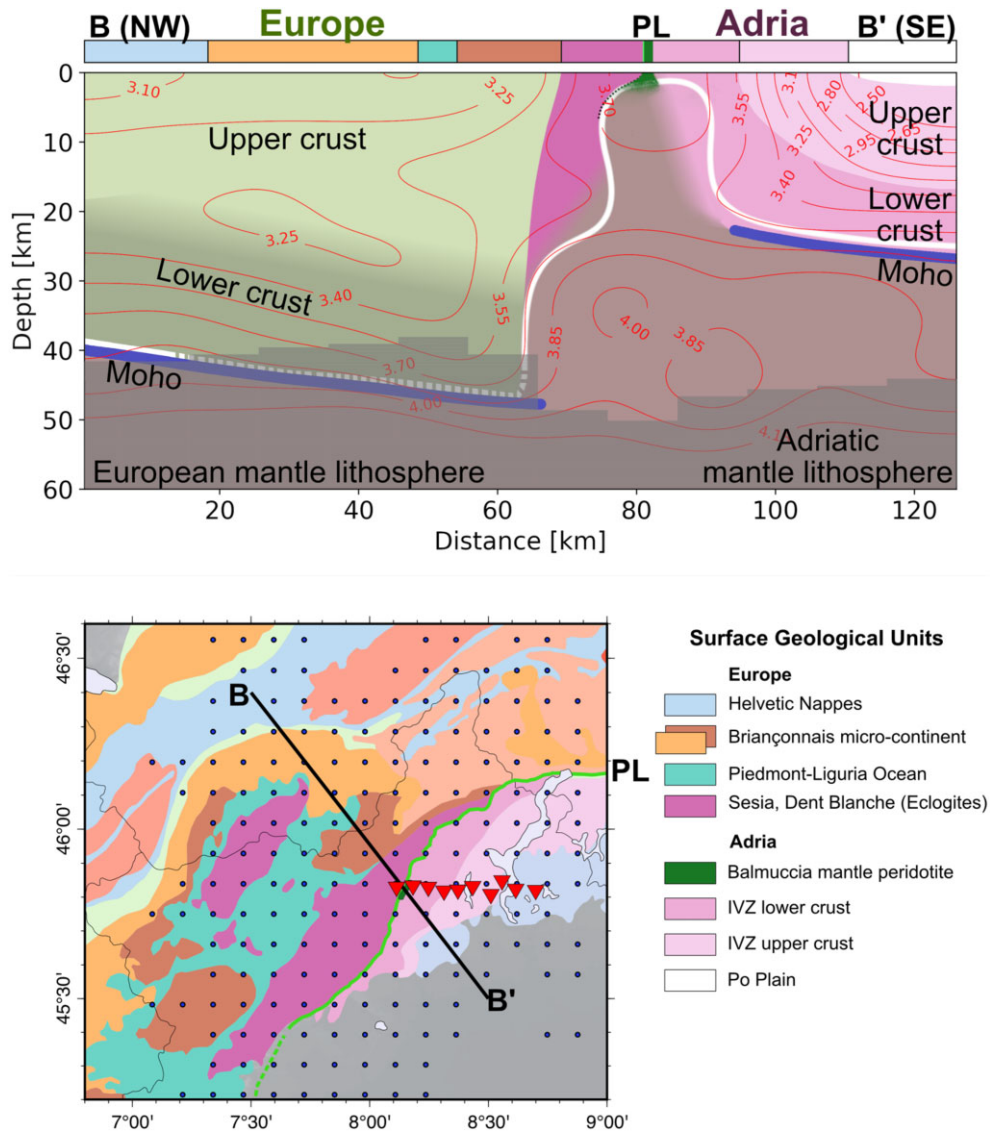


Figure 9. Geophysical interpretation of the v_s model obtained in this study, along profile P2 crossing the PL. The top banner shows the tectonic units at the surface along the profile, as mapped in Figs 1 and 6(d) and in the inset below. The ‘Surface Geological Units’ legend provides the colour code. In the interpretation plot, red lines represent the v_s iso-contours (in km s^{-1}) of the final model; blue lines identify the Moho on both the European and the Adriatic sides, traced after Spada *et al.* (2013); the white curve contours the physical structures associated with the IGB anomaly. Grey-shaded areas indicate parts of the model, where the sensitivity kernels have amplitudes lower than 5 per cent of their maximum, across all the periods of interest. We use green for European crust; white and pink for Adriatic sediments and crust; purple for eclogite rocks; green for mantle peridotite and brown for European and Adriatic mantle.

beneath the IVZ area. In addition to the IGB features, we also resolve second-order velocity variations in the neighbouring regions, featuring a slower European lower crust with respect to its Adriatic counterpart. We also resolve a deeper positive velocity increase, which agrees well, to the first order, with the Moho discontinuity previously mapped by Spada *et al.* (2013). Moreover, we resolve the faster IGB structure where the previous Moho map presented a gap.

We also observe agreement between the IGB velocities and the physical properties of the rock samples collected in the IVZ and analysed in the laboratory (Zappone & Kissling 2021). By also considering the density value ranges indicated by Scarponi *et al.* (2020, 2021), we argue that the bulk of the IGB may consist of a combination of mantle peridotite, ultramafic and lower crustal rocks. The current ANT model cannot resolve the signature of a potentially buried former Moho transition zone for the IVZ, which

still constitutes a question of great interest and is worth future investigation with higher resolution approaches. Thanks to the dense IvreaArray seismic data, the new IGB model is more detailed and complex with respect to the iconic and long-time referred to as ‘Bird’s head’ model by Berckhemer (1968).

Our new findings, based on new v_s constraints in 3-D, corroborate the model of a continuous mantle-like body extending from the IVZ surface down through the whole crust, similarly to the recent interpretation of Ryberg *et al.* (2023) based on control source data v_p tomography. This further suggests that the Balmuccia peridotite unit may not constitute an isolated lens, as previously hypothesized (e.g. Quick *et al.* 2003), and that the crustal cross-section exposed at the surface in the IVZ may have been tilted with minor internal deformation during the continental collision (e.g. Zingg *et al.* 1990). The direct analysis of new local rock samples expected from the outcome of the scientific drilling project DIVE may shed further

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