- 1 Temporal variations of seismicity rates and Gutenberg-Richter b-values for a stochastic
- 2 declustered catalog: an example in central Italy
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#### **ABSTRACT**

- One important aspect of the seismicity is the spatio-temporal clustering; hence, the distinction between
- 18 independent and triggered events is a critical part of the analysis of seismic catalogs. Stochastic
- declustering of seismicity allows a probabilistic distinction between these two kinds of events. Such
- an approach, usually performed with the ETAS model, avoids the bias in the estimation of the
- 21 frequency magnitude distribution parameters if we consider a subset of the catalog, i.e. only the
- 22 independent or the triggered events. In this paper we present a framework to properly include the
- probabilities of any event to be independent (or triggered) both in the temporal variation of the seismic
- rates and in the estimation of the *b*-value of the Gutenberg-Richter law. This framework is then applied

to a high-definition seismic catalog in the central part of Italy covering the period from April 2010 to December 2015. The results of our analysis show that the seismic activity from the beginning of the catalog to March 2013 is characterized by a low degree of clustering and a relatively high *b*-value, while the following period exhibits a higher degree of clustering and a smaller *b*-value.

The seismic hazard assessment and, in general, the capability of identifying possible correlations

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#### INTRODUCTION

between the variations of the Earth crust physical properties and the space-time seismicity distribution, needs a reliable statistical analysis of the seismic catalogs. The possibility of performing reliable statistical analyses is certainly related to the use of estimation methods that must be robust and independent of the researcher's subjective choices; for this reason, we propose a series of procedures of seismic catalogs analyses characterized by a high degree of objectivity and robustness, finalized to the estimation of the seismicity rates and Gutenberg-Richter *b*-values (Gutenberg and Richter, 1944) temporal variations. A first essential step to conduct a careful and conscious study of the seismicity, in addition to a deep knowledge of the catalog and its problems (e.g., catalog completeness), is represented by the so-called declustering process. The declustering process consists in the separation of the independent events from the earthquakes which depend on each other's (triggered events). This distinction is mainly finalized to collect different information about the earthquake potential estimation. In fact, while independent earthquakes are generally associated with secular tectonic phenomena, the triggered events are mainly attributed to stress variations caused by previous events (Aki, 1956; Knopoff, 1964). Currently, there are several approaches for declustering a seismic catalog. In the seismological literature, the most used techniques can be divided into four big categories: window-based methods (e.g., Utsu, 1969; Knopoff and Gardner, 1972; Gardner and Knopoff, 1974; Keilis-Borok and

49 Kossobokov, 1986), link-based methods (e.g., Savage, 1972; Reasenberg, 1985; Frohlich and Davis, 50 1990; Davis and Frohlich, 1991) stochastic methods (e.g., Kagan and Jackson, 1991; Zhuang et al., 51 2002; Console et al., 2010a) and correlation metric methods (e.g., Baiesi and Paczuski, 2004; 2005; 52 Zaliapin *et al.*, 2008; Zaliapin and Ben-Zion, 2013a; 2013b). 53 These methods are mainly distinguished by the different models used to characterize the independent 54 events. In detail, the window-based, the link-based and the correlation metric methods have a 55 deterministic and dichotomic approach in the different attributes' selection, classifying an earthquake 56 as either a mainshock or an aftershock or considering a-priori values for the parameters in the 57 Gutenberg-Richter scaling law. 58 On the other hand, in the stochastic approaches, the background seismicity separation from the 59 clustering components is executed starting from the attribution of probability for each event being 60 triggered by another previous event or being an independent event. In the algorithm proposed for the 61 first time by Zhuang et al. (2002), these probabilities are computed through the background intensity 62 estimation, considered as a space function constant with time, and through the definitions of parameters 63 associated with the clustered structures obtained by the epidemic-type aftershock sequence (ETAS) 64 model. Although the choice of the best declustering approach is related to the specific pursued goals 65 and to the catalog features (e.g., epicenter and source depth distributions, van Stiphout *et al.*, 2012), 66 the stochastic methods present an approach that avoids subjective choices. Such objectivity makes 67 these methods more reliable than the deterministic methods which assume arbitrary values for some 68 declustering parameters definition, such as the space-time distance in which mainshocks act. 69 Moreover, as reported in the work of Mizrahi *et al.* (2021) the ETAS declustering processes appear to be the only declustering algorithms able to avoid bias in the *b*-value estimation for the declustered 70 71 catalogs. The *b*-values are in fact strongly underestimated when the catalog declustering is executed

72 using window-based and link-based methods (e.g., Marzocchi and Taroni, 2014; Azak et al., 2018; 73 Mizrahi et al., 2021). 74 However, a correct and reliable seismicity rate and b-value estimation will be also related to the 75 definition of the separation criterion to be used to attribute the different probabilities obtained by the 76 stochastic declustering processes to the background and triggered contributes. Generally, in many 77 studies these contributions are separated by choosing a threshold probability of independence (or 78 triggered), with a purely subjective approach to the problem (e.g., Pintori et al., 2021). Instead, in other 79 cases more complicated procedures have been shown: e.g., in the work of Ueda and Kato (2019) the 80 background rate is obtained by averaging the different background rates built starting from a big 81 number of stochastic declustered catalogs. 82 In this paper, we adopt an easier strategy for the definition of the independent and triggered seismicity 83 rates, based on the sum of the probabilities for the seismic events to be independent or triggered, 84 respectively. Such probabilities can also be used as weights to perform the *b*-value estimation for the 85 background seismicity and for the clustered seismicity (Zhuang et al., 2004). So, by associating the 86 weights obtained by the stochastic declustering with robust *b*-value estimation methods (Taroni *et al.* 87 2021b), it is possible to build *b*-value time series characterized by a high degree of reliability. For this 88 work, we considered an Italian high resolution catalog of natural seismicity, recorded by the TABOO 89 (The Alto Tiberina Near Fault Observatory) multidisciplinary research infrastructure managed by the 90 Istituto Nazionale di Geofisica e Vulcanologia (INGV) (see "Dataset" section) (Chiaraluce et al., 91 2014). Starting from this catalog we have built seismicity rates and Gutenberg-Richter *b*-values time 92 series using the declustering algorithm based on the ETAS-2D Model by Console *et al.* (2010b).

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#### **DATA**

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**Dataset** 

TABOO is part of the community of the NFOs (Near Fault Observatories) that was built within the FP7 European project NERA – Network of European Research Infrastructures for Earthquake Risk Assessment and Mitigation (2010- 2014). This community presently consists of six multidisciplinary 101 research infrastructures operating in regions characterized by high seismic hazard. NFOs are now part 102 of the European Plate Observing System -Thematic Communities (Chiaraluce et al., 2022). NFOs collect multi- parametric near- fault data providing both raw data and advanced scientific products 104 through the EPOS-related services. The TABOO target area is located along the upper Tiber Valley (northern Apennines of Italy, see Figure 1) where the Alto Tiberina Fault (ATF), an east-dipping low angle normal fault (dip 15°- 25°), dominates at depth an extensional fault system active in the Quaternary (Pialli et al., 1998, Mirabella et al., 2011, Barchi et al., 1998, Boncio et al., 2000, Chiaraluce *et al.*, 2014). This area perfectly fits the basic rules for being an NFO: it hosts active faults; it is relatively small; it is characterized by a relatively high seismicity. As this area was chosen as an NFO, the Italian National Seismic Network held by INGV was here progressively complemented with 111 additional permanent seismic stations since January 2009, adjuvated by a short-term experiment (24 temporary stations were active between April 2010 and February 2011) and it was also progressively instrumented with several other multidisciplinary monitoring systems. 114 The INGV seismic network in the TABOO area before the NFO implantation consisted of 26 stations with minimum and median inter-distances of 6 km and 71 km, respectively (see Figure 1) while, 116 excluding the temporary stations, it now consists of 55 stations with minimum and median interdistances of 1 km and 50 km, respectively since 2010. Nevertheless, it is worth noting that the stations 118 characterized by inter-distances as small as 10 to 30 km are prevalent within the network. This greatly improves the locations' quality, especially of the depth, keeping the closer station distance low. The

catalog used in the present paper was built by combining in a fully automatic work-flow (Di Stefano et al., 2014), a sensitive events detection, a high quality, P- and S-onset picking and weighting system (Di Stefano et al., 2006; Aldersons et al., 2018), a local tomographic 3D velocity model built on purpose for the automatic workflow (Di Stefano et al., 2014) and a robust 3d tomographic and location code (SimulPS, Thurber, 1983; Ebenhart-Phillips, 1986; 1990). Finally, the resulting ~135k earthquakes where quality selected for RMS ( $\leq 0.3$ ), number of phases ( $\geq 10$ ), maximum GAP ( $\leq 270$ ), maximum horizontal and vertical location errors ( $\leq 1.5$ km) and minimum number of stations with  $M_{\rm L}$ estimation (≥ 5). The final dataset consists of ~50k high-quality located earthquakes from April 2010 to December 2015.  $M_{\rm L}$  is calculated, for each event, as the median (with related standard deviation) over all the available stations'  $M_L$ . Stations'  $M_L$  are calculated by applying a derived attenuation law for the TABOO zone (Marzorati and Cattaneo, 2016) to the mean of the two horizontal channels' amplitude. Amplitudes in their turn are automatically estimated as the maximum peak-to-peak elongation of the signal after the convolution to standard Wood-Anderson sensor. A specificity of the applied method is the use of an adaptive band-pass pre-filtering. The algorithm automatically finds the optimum lower and upper corner frequency for the specific channel seismogram (sensor-earthquake couple) in the frequency range where signal to noise ratio is higher (over a given threshold of 5), so to better preserve also the signal of smaller magnitude events. Maximum elongation is searched in a window extending from the automatic P-arrival, to 5s beyond the automatic/theoretical S-arrival time. The combination of the TABOO dense seismic network and the use of this adaptive filtering approach allowed a very low threshold in seismic event detection (M. around 0.2) and a very low completeness magnitude of the catalog ( $M_c = 0.5 M_L$ ).

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# **Catalog Analysis and Completeness magnitude estimation**

The high-resolution TABOO catalog contains inside the volume (lat 42.6-44.2 N/lon 11.5-35.5 E) (-1.5<depth (km)< 34.16) 50,483 events from 1 st April 2010 up to 5 th December 2015, the last date on which the catalog was updated. TABOO catalog reports an abundance of small earthquakes that can help better characterize for this area the fundamental scaling laws of statistical seismology. The magnitude range starts from -2.77  $M_L$  to a maximum magnitude equal to 4.01 obtained for the 28 th August 2010 earthquake with coordinates 12.670° E - 42.831° N at a depth of 7 km occurred 14 km south of Foligno (Perugia) (Figure 1). The check of the quarry blasts inside the area by the catalog of non-tectonic earthquakes in Central-Eastern Italy, NTSEQS (Ladina et~al.~2021) shows 191 artificial events that were removed from the dataset.

We focus our analysis inside the polygon, shown in Figure 1, which contains the major part of the seismicity along the Alto Tiberina low angle normal fault system (ATF) and Gubbio Fault (GF). In Table 1 the events with  $M_L \ge 3.5$  are reported. The analysis of the events in depth shows that the major part of the seismicity is contained down to 15 km and as an additional check to be sure that we have deleted all the quarry blasts, we only analyze the dataset inside the depth range between 0.5 and 15.0 km.

One of the most important parameters for the statistical analysis of seismicity (and in particular the *b*-value) is the determination of the catalog's minimum completeness magnitude, *Mc*. Different techniques have been suggested to estimate *Mc*, like the Entire-magnitude-range method, the Maximum curvature-method, Goodness-of-fit test and *Mc* by *b*-value stability (e.g., Ogata and Katsura, 1993; Rydelek and Sacks, 1989; Wiemer and Wyss, 2000; Cao and Gao, 2002).

We follow the approach suggested by Herrmann and Marzocchi (2021) as it is a conservative technique

to determine the Mc of high-resolution earthquake catalogs. Consequently, we use the Lilliefors test (Lilliefors, 1969) as a statistical goodness-of-fit test with the exponential distribution to determine the lowest magnitude cut-off above which the magnitude is exponentially distributed. In other words, above  $Mc^{Lilliefors}$ , the frequency magnitude distribution (FMD) is consistent with the exponential-like Gutenberg–Richter relation. The p-value expresses the probability to observe the data sample assuming that the exponential distribution is true. We use a p-value with a significance level of p=0.1, conservative in a statistical sense (Clauset et~al., 2009) to obtain the lowest magnitude level above which the FMD can be considered exponential. In Figure 2 the results of this analysis are reported. For our dataset (01/04/2010-05/12/2015) we obtain a  $Mc^{Lilliefors} = 0.5$  with a total of 6531 events (0.5<depth (km)  $\leq$ 15.0), which will be the dataset that we will use for subsequent analyzes. Further details about the completeness magnitude computation and its influence on the b-value estimation are reported in Supplemental Material-Texts S1 and S2 respectively.

#### **METHODS**

#### ETAS 2D model

The model applied in this study is based on the Epidemic Type Aftershock Sequence (ETAS) method and is used for an epicentral analysis (2D) of seismicity where depth has not been taken into account (ETAS 2D) (see e.g., Ogata, 1998 and 1999; Console and Murru, 2001; Console *et al.*, 2003). ETAS is a point process model which assumes that the earthquake sequence is made up of aftershocks and background events. Aftershocks include those events that are triggered by other earthquakes while background events are those that occur independent of other earthquakes. A few basic power laws, typical of complex systems are used: i) the Omori-Utsu (Utsu 1961, Ogata 1983) for the temporal

decay of the triggered events, and ii) the Utsu-Seki (Utsu and Seki, 1955) that describes the dependence
of the number and spatial distribution of triggered earthquakes with the mainshock magnitude (see also
Kanamori and Anderson, 1975).

One of the most remarkable features of such a model is that the magnitude of the triggered earthquakes
is randomly sampled from a frequency-magnitude distribution, usually a Gutenberg-Richter law

is randomly sampled from a frequency-magnitude distribution, usually a Gutenberg-Richter law (Gutenberg and Richter, 1944). This implies no distinction between foreshocks, mainshocks, and aftershocks (e.g., Felzer *et al.*, 2004) that can be identified only "a posteriori". In other words, there is no specific preparatory phase before a large earthquake because its probability is only proportional to the seismicity rate.

For the model, the expected number of earthquakes above  $M_{min}$  ( $M_{min} \ge Mc^{\text{Lillieforse}}$ ) in the epicentral space-time unit window, given the observations before time t, at epicentral location  $\overrightarrow{x}$  can be generically described as follows:

$$\lambda(t, \vec{x}) = v\mu(\vec{x}) + \sum_{i:t_i < t} \frac{k}{(t - t_i + c)^p} \left(\frac{(d_0 10^{\alpha(M_i - M_{min})})^2}{(d_0 10^{\alpha(M_i - M_{min})})^2 + |\vec{x} - \vec{x_i}|^2}\right)$$
[1]

205 Where:

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- *v* is a failure rate factor that represents the fraction of spontaneous events (i.e., the ratio between the expected number of independent events and the total number of events, ranging between 0 and 1);
- 208  $\mu(\vec{x})$  represents the rate density of the long-term average seismicity;
- 209  $t_i$  defines the occurrence time of earthquakes;
- 210 k is the productivity coefficient;
- 211 − *c* is the time constant of the Omori law;
- 212 p is the exponent of the Omori law:

-q is the exponent of the epicentral spatial distribution of triggered events;

-  $d_0$  is the epicentral characteristic triggering distance of an earthquake of magnitude  $M_{\min}$ ;

-  $M_i$  is the magnitude of each earthquake considered;

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-  $\alpha$  is the coefficient of the exponential magnitude productivity law.

The epicentral smoothed total time-independent rate-density function  $\mu$ () is computed using the method introduced by Frankel (1995), described in detail by Console and Murru (2001) and Console et al. (2003). The correlation distance used in the exponential kernel distribution of the smoothing algorithm was found to be 4 km. It was determined by maximizing the likelihood of the seismicity in half of the catalog under the time-independent model obtained from the other half and vice-versa. The expression of the summation in equation [1] represents the triggering kernel that depends on time, space, and magnitude. It considers the contribution of every previous event based upon the magnitude of triggering events, the epicentral spatial distance of triggering earthquakes, and the time interval between the triggering event and the forecast. This part is predominant during a sequence. The free parameters of the model (k, c, p, q, d) are estimated by the maximum likelihood method. The parameter v is not determined from the best fit in the learning phase because it is related to all of the other parameters of the model. In the second step of the smoothing algorithm, the events receive a weight proportional to the probability of being independent, with a number between 0 (if the event is totally triggered) and 1 (if the event is totally independent) (Console *et al.*, 2010a), as in the method introduced by Zhuang *et al.* (2002). These weights were adjusted following an iterative procedure similar to that adopted by Marsan and Longliné (2008). The final maximum-likelihood best-fit parameters of the ETAS model applied to our data-set are shown in Table 2.

With this approach it is possible to assign to each event a weight equal to the probability to be independent without the need of removing events from the catalog.

#### Number of occurrences estimation in time

The strategy here used to separate the seismic occurrences for the different seismicity contributions is based on the probability of an event to be independent and its complementary value, estimated by the ETAS declustering process. In detail, in order to obtain the occurrence number of independent events  $(Sb_k)$  at the k-time window, we considered the sum of independence probabilities  $\phi(i)$  for each earthquake until the ith event, as reported in equation [2]:

$$Sb_k = \sum_{i} \varphi \qquad \qquad [2]$$

In this way the independence probabilities acting as weights will allow us to compute the background occurrences simply by giving a different importance to the different earthquakes recorded in the catalog. The greater the independence probability of an event, the greater its weight in the estimation of background occurrences and vice versa.

Following the same approach and defying the triggered probability as:

$$\varrho_i = 1 - \varphi_i \tag{3}$$

the occurrence number of clustered seismicity at the k-th window (  $Sc_k$ ) will always be expressed as the sum of these probabilities:

$$Sc_k = \sum_{i} 1 - \varphi \quad _i$$
 [4]

This method which allows to quickly separate the number of occurrences of the different components of seismicity, appears simple from a mathematical point of view avoiding any type of subjectivism.

#### **Fourier Transform**

In this study, in order to analyze the periodical features of the independent seismicity rate in our dataset, we make use of the definition of the Fourier transform of a time function f(t) as:

$$\Im[f(t)] = F(\omega) = \int_{-\infty}^{+\infty} f(t) e^{-i\omega t} dt$$
 [5]

where i is the imaginary unit.

We apply this definition to the function describing the time history of the seismicity rate by means of a computer code, performing the integral [5] by a numerical discretization. In order to obtain realistic results, an appropriate discretization has to be chosen for the input and output functions. As  $F(\omega)$  is a complex number, we consider just its absolute value  $|F(\omega)|$  in the presentation of our results.

### Estimation of the *b*-value in time

The estimate of the changes in the b-value was performed by the "Weighted Likelihood Estimation" (WLE) approach (Taroni  $et\ al.$ , 2021a). According to this method, the b-value estimate at time t, b(t), is performed considering all the events until the time t, and attributing to each of them a weight that varies according to the temporal distance with respect to time t (Eq. 4 in Taroni  $et\ al.$ , 2021b). In this way, avoiding using a fixed number of events, as defined in the classic "Rolling Window Approach"

(e.g., Gulia and Wiemer, 2019), and therefore avoiding obtaining time windows of different lengths, it is possible to ensure that only the recent events may be relevant in the estimation of the *b*-value, thus obtaining a more robust and objective estimation of *b*-value changes over time. Here the WLE is used both to properly take into account the temporal variation of the seismicity and to correctly consider the weights assigned to each event by the stochastic declustering following Console *et al.* (2010a) technique. Indeed, in order to estimate the *b*-value contributions relating to background  $\hat{b}(t)$  back and triggered  $\hat{b}(t)$  trig is seismicity, we implemented the WLE algorithm through additional weights as reported in the equations [6] and [7] respectively:

$$\hat{b(t)}_{back} = \frac{\sum_{i=1}^{n(t)} W(t_0 - t_i) \varphi_i}{\ln(10) \left(\sum_{i=1}^{n(t)} W(t_0 - t_i) \varphi_i (M_i - M_c) + \frac{\Delta M}{2}\right)}$$
[6]

 $\sum_{n=0}^{n(t)} W(t_n - t_n) \alpha$ 

$$\hat{b(t)}_{trig} = \frac{\sum_{i=1}^{n(t)} W(t_0 - t_i) \varrho_i}{ln(10) \left(\sum_{i=1}^{n(t)} W(t_0 - t_i) \varrho_i (M_i - M_c) + \frac{\Delta M}{2}\right)}$$
[7]

Where  $W(t_0 - t_i)\varphi_i$  and  $W(t_0 - t_i)\varrho_i$  correspond to the weights assigned to each of the n(t) events considered up to time t;  $W(t_0 - t_i)$  is the weight that depends on the time lapse between the  $i_{th}$  event and the first event in the catalog at time  $t_0$ , while the weights  $\varphi_i$  and  $\varrho_i$  are the ones related to the stochastic declustering algorithm, related to the background and triggering probability, respectively;  $M_i$  is the magnitude of the  $i_{th}$  event,  $\Delta M$  is the magnitude binning, and  $M_c$  is the magnitude of completeness of the catalog. Then, using equations [6] and [7], it is possible to estimate the temporal variations of the b-value for the background and triggered events in the catalog, separately. Such an approach also avoids the subjective choice of the number of events used for the temporal estimation of the b-value (usually 100 or 200 events, Taroni et al., 2021b). The importance of recent

events with respect to the earlier is controlled by the weight  $W(t_0 - t_i)$ , defined as  $W(t_0 - t_i) = exp(-\alpha\Delta T)$ , where  $\Delta T$  corresponds to time lapse between the  $i_{th}$  event and the first event in the catalog, and  $\alpha$  is the parameter that regulates the amount of past information relevant in the estimation (this last parameter is objectively estimated with the maximum likelihood approach, as explained in Taroni et al., 2021b). With respect to the equations of Taroni et al., 2021b, here we used non-normalized weights, because our weights are composed by two different factors, then the numerator of equations [6] and [7] is not equal to 1 but is equal to the sum of all the weights considered in the computation.

### **RESULTS**

In this section we present the time series both of seismic rate and Gutenberg-Richter b-value for the TABOO catalog, starting from the ETAS 2D model, composed by 6,523 events recorded from 11 th April 2010 to 5th December 2015. The earthquakes recorded from 1th to 10th April 2010 were not used for this analysis due to the so-called "warm-up" phenomenon, consisting in an unrealistic high probability of independence of the events in the initial part of the catalog, due to the omission of previous triggering earthquakes. The ETAS model in fact associates an independence probability equal to 1 to all those events without information on foreshocks. Therefore, in order to ensure data stability, the first 10 days of the TABOO catalog have been removed.

For the seismic rate analysis, we considered not only the daily variation of the event number that occurred in the whole TABOO catalog, but also the changes related to the background and triggered components. As mentioned above, the separation of the different contributions was possible through the independence probability values obtained from the ETAS declustering algorithm by Console  $et\ al.$  (2010a). In detail, summing the independence probability ( $\varphi_i$ ) (by eq.2) and the triggered probability

 $(\varrho_i)$  (by eq. 4), we have obtained the background and triggered daily seismic rates, respectively. The results of these computations are shown in Figure 3.

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Observing the incremental and cumulative event number distribution in time we can note a twofold behaviour in the earthquake occurrence. The first part of the catalog, from April 2010 to about March 2013, is in fact characterized by a low number of events (about 1456) with an occurrence of about 1.4 earthquakes per day. Moreover, in this time lapse the number of background and triggered events (about 713 and 743, respectively) appears very similar. Instead, in the last years, since March-April 2013 to December 2015, the seismicity rate increased sharply and a largest daily variation has been recorded, with the average occurrence of about 6.5 events per day in a small-time interval from March 2013 to October 2014 (seismic swarms). This earthquake frequency increase appears to be closely related to the triggered events whose number is equal to 4299 in the second part of the catalog, reaching a maximum value of about 3522 events during the year ranging between 2013-2014. On the other hand, though in the last few years the background seismicity is still characterized by a low number of earthquakes (about 772), also for this component the maximum number of occurrences results concentrated during the seismic swarms of 2013-2014, which mainly affected the municipalities of Città di Castello, Gubbio and Pietralunga. The seismic background highlights small variations, which are better visible by analyzing the seismicity rate with a bigger observation window. In fact, observing the monthly behavior of the background (Figure 4a), the non-stationarity of this component appears evident, showing two

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maximum values, one at the beginning of 2011 and the other one in the second half of 2014.

This trend is clearly shown also with a quantitative approach through Fourier transform executed for the background events, where the maximum frequency is defined for a time period of about 40 months (peak at 0.025 in Figure 4b). Given the short duration of the recording of the seismic catalog (5 years) with respect to the oscillation period detected (40 months), whether such variations are linked to a real periodic behavior of the background or whether the maximum occurrence values are due to transient phenomena appears not simple to understand.

For the b-value analysis, as in the previous analysis, we consider the time series of the whole TABOO catalog and also the changes related to the background and triggered components separately. The results of the estimations are reported in Figure 5a, where the black, red and blue lines indicate the b-value time series for the whole catalog, for the background seismicity and for triggered events, respectively. These curves were built estimating forgetting parameter  $\alpha = 0.020$  for our catalog. Further information about the b-values estimation errors in terms of standard deviations are available in the Supplemental Material-Text S3.

values estimated considering all the events of the TABOO catalog are ranging between the *b*-values of the background events (higher) and the *b*-values of the triggered events (lower). In particular, this gap between the different *b*-values appears to be very small in the first three years of the catalog, from April 2010 to about March-April 2013, where the *b*-average values are near to 1.1 both for the entire catalog and for the different components of the seismicity.

As clearly highlighted by the distribution of magnitude over time (Figure 5b), the number of events recorded in these first three years is very low, about 1/6 of that reported in the entire catalog. However, starting from April 2013, the different behavior between the *b*-values of background and *b*-values of

Observing the curves reported above, we can note that for the entire duration of the recording, the *b*-

triggered seismicity appears more evident. In fact, while for the background events the b-values

oscillate always around an average of about 1.1, for the triggered events the *b*-values show a sharp reduction reaching average values of about 0.8-0.9. This different behavior of *b*-values estimated for the different components of seismicity is in line with the observations of Chiaraluce et al., 2007 and Valoroso et al., 2017, which mainly attribute this difference to the different structures responsible to generate independent events or triggered events. According to these authors, in fact, while the background seismicity is mostly attributable to the lowangle Alto-Tiberina fault (ATF), for which a number of events homogeneously distributed in time and space are evident, the triggering seismicity, characterized by multiple seismic sequences recorded mainly starting from April 2013 (Figure 5b), should instead be associated with the activity of the synthetic and antithetic faults placed on the ATF hanging wall. Therefore, in the geological framework of the Alto-Tiberina fault system, the global *b*-value appears strongly affected by the triggered seismicity which is predominant in this study area, with a number of events equal to about 5042 out of a total number of 6523 events recorded. It is in progress a work that will examine the time and space variations of the seismicity rates and the Gutenberg-Richter *b*-values for the Alto Tiberina fault system, also taking in account the depths of events recorded in the TABOO catalog, through the construction of a new ETAS 3D model.

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#### CONCLUSIONS

As demonstrated by numerous studies (e.g., Scholz 1968, 2015; Wiemer and Wyss, 1997; Wiemer *et al.*, 1998; Oncel and Wyss, 2000; Wyss *et al.*, 2001; Schorlemmer *et al.*, 2005; Murru *et al.*, 2005; Murru *et al.*, 2007; Meletti *et al.*, 2008; Bachmann *et al.*, 2012; Tormann *et al.*, 2014, 2015), *b*-values fluctuations could be related with physical proprieties and dynamism of the Earth crust. In particular, the recent work of Gulia and Weimer (2019) highlighted how the *b*-value temporal evolution could have a predictive meaning in the upcoming large-event occurrence. For these reasons, reliable

computation of the b- value time series represent an important instrument for a specific zone in the seismic hazard assessment. Therefore, in this work, we wanted to present a series of procedures finalized to an objective analysis of seismic catalogs to minimize biases in the b-value temporal variation estimation for background and clustered seismicity. In detail, to separate the different contributions of seismicity we proposed a new approach for the analysis of stochastic declustered catalogs based on the use of weights obtained from the independence probabilities, achieved through the construction of the ETAS 2D model. Thanks to our simple but rigorous approach that applies a criterion not affected by subjective choices, the estimation of the seismic rates and Gutenberg-Richter b-value time variations both for independence and triggered earthquakes is possible. For demonstration purposes we applied this study to a high-resolution catalog. However, the procedures shown can also be used for classical instrumental seismic catalog. In detail, this analysis executed on TABOO catalog allowed to separate the background and clustered contributions for the Alto-Tiberina seismic area, highlighting how the variations in the seismic rates and in the *b*-values are mainly related to the triggered events that appear predominant in terms of number of occurrences in the considered time period. Moreover, the seismic rate time series analysis puts in evidence the nonstationarity for background seismicity, in which the biggest oscillations showed mostly a three-years frequency. Regarding the b-value time series analysis, the estimations suggested a higher b-value for background events with respect to triggered events.

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### **DATA AND RESOURCES**

The dataset considered in this work is generated by The Altotiberina Near Fault Observatory (TABOO), an Istituto Nazionale di Geofisica e Vulcanologia monitoring infrastructure. This infrastructure is part of the European Plate Observing System - Implementation Phase (EPOS-IP)

405 project, available at http://www.epos eu.org, which received funding from the European Union's 406 Horizon 2020 research and innovation program under grant agreement 676564. 407 Query blasts analysis was executed considering the "Catalog of non-tectonic earthquakes in Central-408 Eastern Italv" redacted from the Ancona section of the INGV, available at 409 http://www.an.ingv.it/NTSEQS 410 The *b*-value time series built through the "Weighted Likelihood Approach" were obtained using the 411 code by Taroni *et al.* (2021) available at: 412 GitHub - MatteoTaroniINGV/Bvalue\_TimeSeries\_WeightedLikelihoodEstimation 413 All the graphs reported in the figures were made using Matlab codes 414 Figure 1 was made using Generic Mapping Tools (GMT) software (Wessel et al., 2013). 415 The Supplemental Material for this article includes further information about the reliability of *b*-value 416 time series estimation. In particular, we focused on a) the magnitude of completeness estimation b) the 417 influence of changes in completeness magnitude on the *b*-value time series and on c) the computation 418 of *b*-values standard deviations. 419 **ACKNOWLEDGEMENTS** This work was supported by the 2020-2023 INGV Department Strategic Project named MUSE 420 421 Multiparametric and mUltiscale Study of Earthquake preparatory phase in the central and northern 422 Apennines. We wish to thank the two reviewers for their valuable comments. We also thank the Editors 423 of SRL for their support and encouragement.

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# Tables:

**Table 1**. The strongest events with  $M_L \ge 3.5$  in the area drawn from the polygon (Figure 1)

Province	Date (dd/mm/yyyy)	Latitude (degree)	Longitude (degree)	Local Magnitude $(M_{ m L})$	Depth (km)
Pietralunga (PG)	15/04/2010	43.47	12.43	3.5	4.09
Gubbio (PG)	18/12/2013	43.38	12.52	3.6	3.18
Gubbio (PG)	22/12/2013	43.38	12.51	3.8	3.72

**Table 2.** Best-fit parameters of the ETAS 2D model optimized over the study period (1 April 2010–5 December 2015).

Parameter	Value
Number of events with $M \ge 2.1$	6,531
Lower magnitude threshold of triggering events	0.5
Lower magnitude threshold of target events	0.5
$k$ (days $p^{-1}$ ) Productivity coefficient	5.34
<i>c</i> (days) Time constant in Omori law	0.02
<i>q</i> Exponent of the epicentral spatial distribution of triggered events	2.21
p Exponent in Omori law	1.16
$d_0$ (km) Characteristic triggering distance in the spatial distribution	0.2
v Fraction of spontaneous events	0.23
$lnL_1$ Maximum log-likelihood of the catalog under the clustering hypothesis	96,042.87
$lnL_0$ Maximum log-likelihood of the catalog under the Poisson hypothesis.	64,127.69
$dlogL = ln(L_1/L_0)$ Log-likelihood ratio	31,915.17

# List of figure captions:

**Figure 1.** Epicentral distribution of all events falling within the TABOO area in the time period 1 April 2010 - 5 December 2015. The black polygon highlights the analyzed area. The ATF and GF are shown with red and yellow lines, respectively. The main municipalities are also indicated with yellow squares. The red and green triangles show permanent and temporary stations, respectively. The inset map shows the location in Italy of Figure 1.

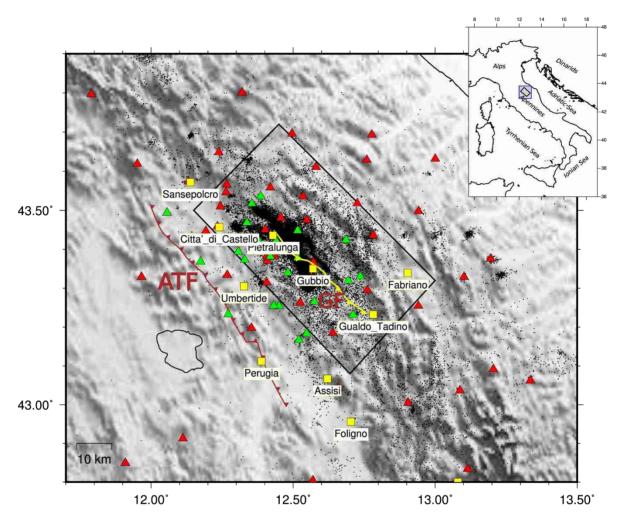
**Figure 2.** Magnitude distribution for the TABOO catalog inside the polygon shown in Figure 1, for the time period 1 April 2010 - 5 December 2015. The left upper panel (a) shows the Lilliefors *p*-value as a function of *Mc*, considering all the dataset magnitudes. The horizontal dashed line in red indicates

674 the significance level, 0.1, above which the FMD can be considered exponential. The right upper panel 675 (b) the magnitude frequency distribution, considering all the dataset magnitudes. The red and blue dots 676 indicate the exponential distribution and the cumulative number of events, respectively. The yellow vertical line indicates the considered Mc Lilliefors. The bottom panel (c) is the sequential number of the 677 678 events versus the magnitude from 1 to 6531, which corresponds to the first and last event of the dataset, 679 respectively. 680 **Figure 3.** (a) Incremental number and (b) cumulative number of events daily recorded in the TABOO 681 catalog from 11 April 2010 to 5 December 2015. The black, red and blue lines indicate the entire 682 earthquake in the catalog, the independence and triggered events, respectively. 683 **Figure 4.** (a) Estimated number of background events occurred monthly (30 days); (b) frequency 684 spectrum of the background seismicity computed through the Fourier Transform. 685 **Figure 5.** (a) *b*-value time series estimated using the weighted likelihood approach. The black line 686 refers to all events recorded in the TABOO catalog, while the red line and the blue line are the *b*-values 687 for background and clustered seismicity, respectively. (b) Magnitude earthquakes distribution over 688 time. 689 690

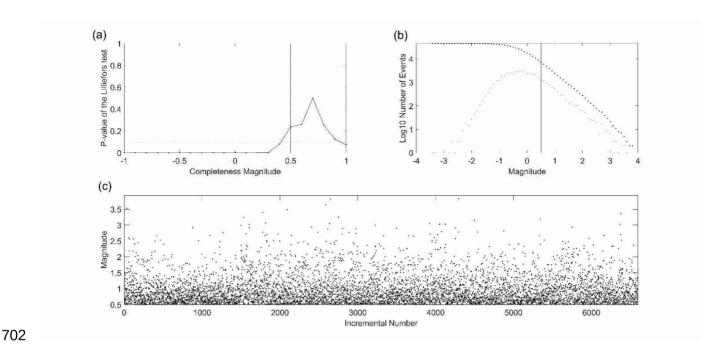
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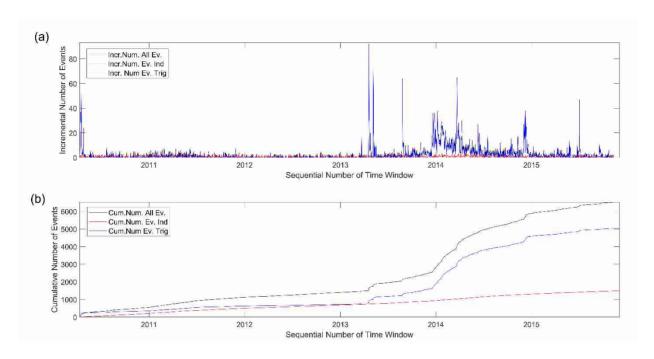
# 694 Figures:



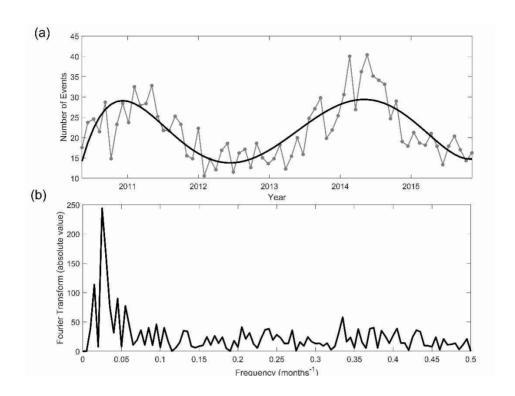
**Figure 1.** Epicentral distribution of all events falling within the TABOO area in the time period 1<sup>st</sup> April 2010 – 5<sup>th</sup> December 2015. The black polygon highlights the analyzed area. The ATF and GF are shown with red and yellow lines, respectively. The main municipalities are also indicated with yellow squares. The red and green triangles show permanent and temporary stations, respectively. The inset map shows the location in Italy of Figure 1. The color version of this figure is available only in the electronic edition.



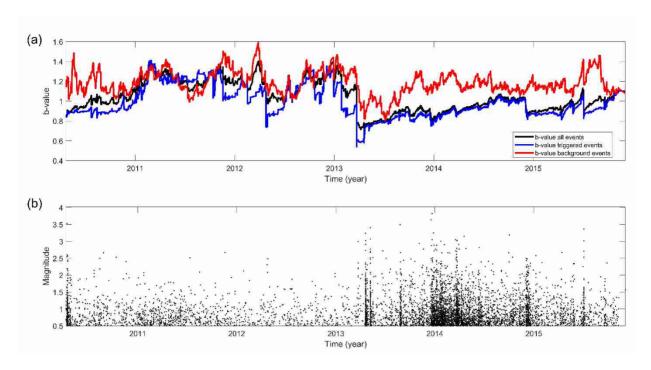
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**Figure 3.** (a) Incremental number and (b) cumulative number of events daily recorded in the TABOO catalog from 11<sup>th</sup> April 2010 to 5<sup>th</sup> December 2015. The black, red and blue lines indicate the entire earthquake in the catalog, the independence and triggered events, respectively. The color version of this figure is available only in the electronic edition.



**Figure 4.** (a) Estimated number of background events occurred monthly (30 days); (b) frequency spectrum of the background seismicity computed through the Fourier Transform.



**Figure 5.** (a) *b*-value time series estimated using the weighted likelihood approach. The black line refers to all events recorded in the TABOO catalog, while the red line and the blue line are the *b*-values for background and clustered seismicity, respectively. (b) Magnitude earthquakes distribution over time. The color version of this figure is available only in the electronic edition.

Figure 1 Click here to a

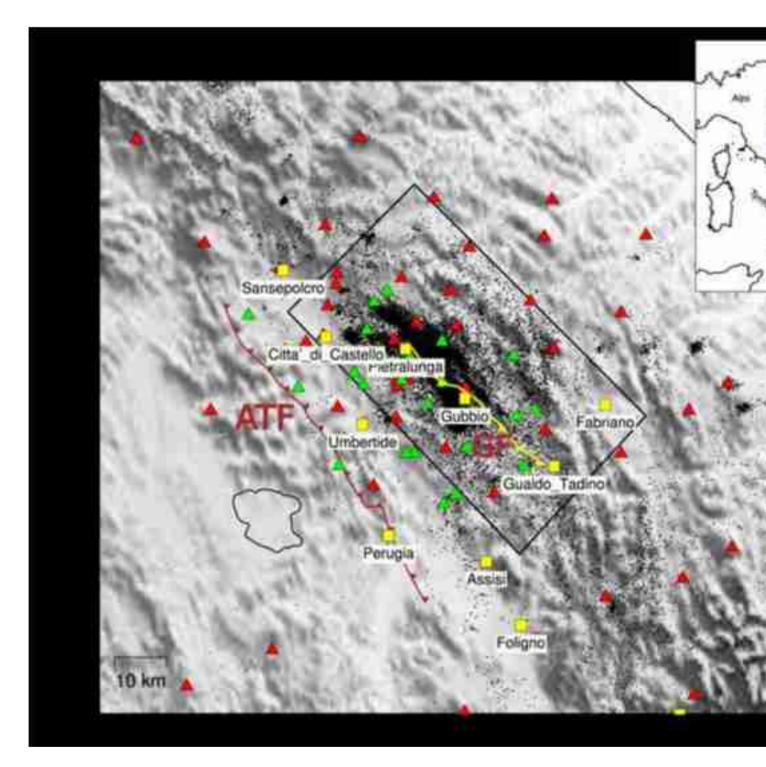


Figure 2 Click here to a

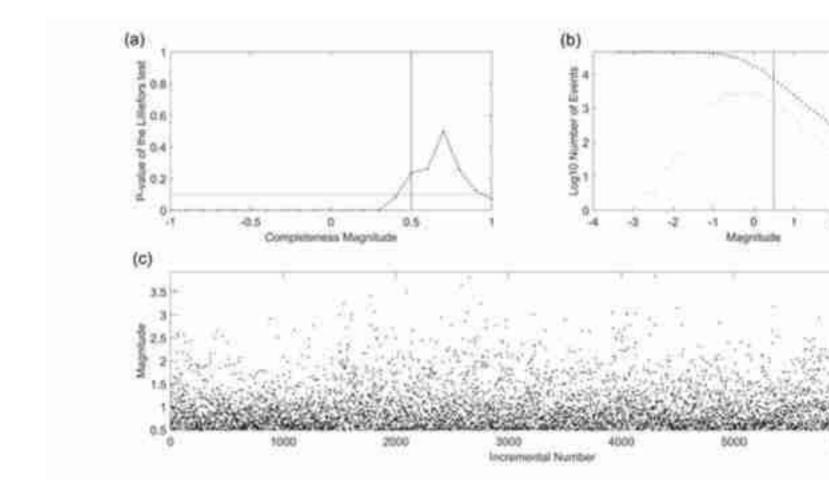


Figure 3 Click here to a

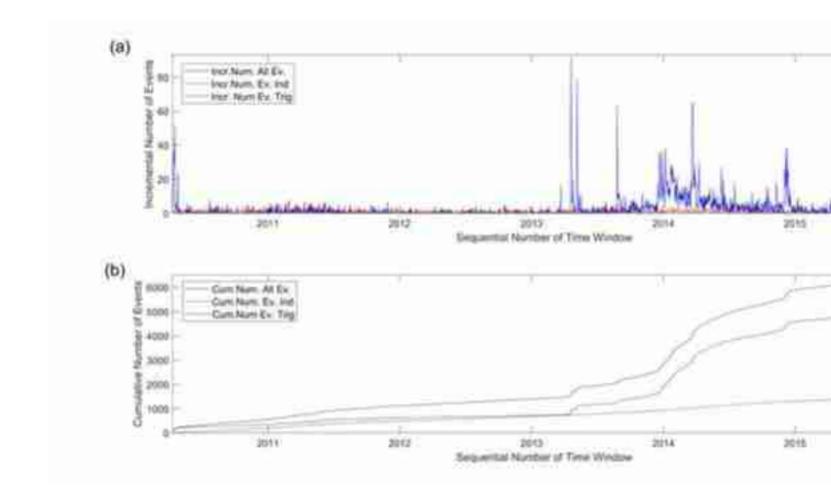


Figure 4 Click here to a

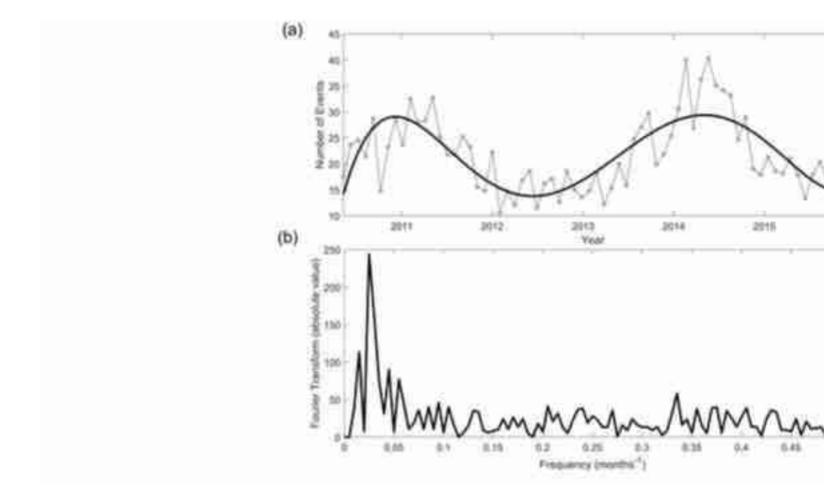
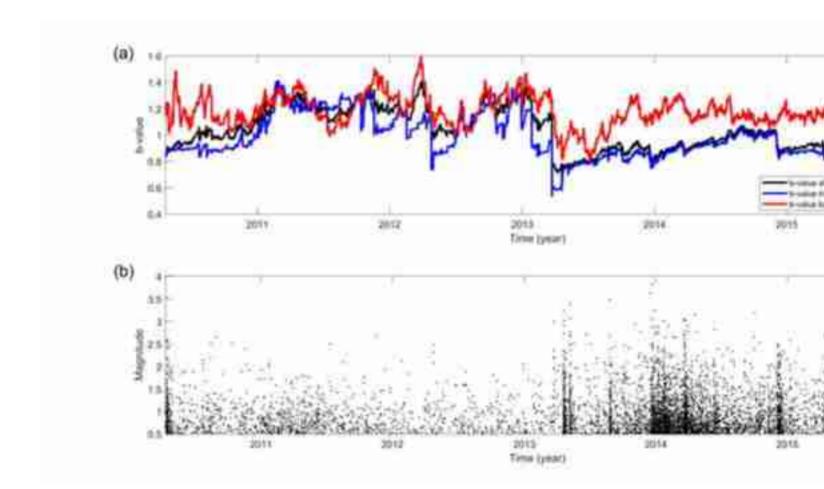


Figure 5 Click here to a



- 1 Temporal variations of seismicity rates and Gutenberg-Richter b-values for a stochastic
- 2 declustered catalog: an example in central Italy
- 3 Anna Eliana Pastoressa, Maura Murru, Matteo Taroni, Rodolfo Console, Caterina Montuori,
- 4 Giuseppe Falcone, Raffaele Di Stefano

# 6 **Description of the Supplemental Material**

- 7 In this document we report further information about the reliability of *b*-value time series estimation.
- 8 In particular, we show a detailed description of approaches and procedures used to define the
- 9 magnitude of completeness, also analysing *b*-value robustness with respect to completeness variation.
- 10 Finally, in the last section, information about the computation and meaning of *b*-value standard
- 11 deviation is reported.

### 13 Text S1

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## Magnitude of completeness estimation

15 In this work we performed a detailed magnitude of completeness estimation. We used one of the most

conservative methods to compute the magnitude of completeness, i.e., the method suggested by

Herrmann and Marzocchi (2021), based on the Lilliefors test (Lilliefors, 1969). Furthermore, we also

investigated the so-called Short Term Aftershock Incompleteness (STAI), i.e. the temporal

incompleteness that can affect seismic catalogs after the strongest events (Lolli and Gasperini, 2006).

To deal with this problem, we applied the method proposed by Zhuang *et al.* (2017): this method

consists in plotting the incremental number of events vs magnitude. In the case of STAI, in the lower

part of the plot some empty spaces will appear (see e.g. Figure 2 of Zhuang et al. 2017). In our Figure

2c of the manuscript, there are no empty spaces in the lower part of the plot: then we can assert that

the estimated magnitude of completeness  $M_{cilliefors} = 0.5$  is not affected by STAI, and it can be 24 25 considered a reliable magnitude of completeness for the entire duration of the catalog. 26 27 Text S2 Influence of changes in completeness magnitude on the *b*-value estimation 28 29 Here we show the estimation of the *b*-value temporal variations with two conservative thresholds for 30 the magnitude of completeness: 0.75 and 1.00. The results obtained are coherent with the ones relative 31 to the magnitude of completeness of 0.5. 32 33 34 Text S3 35 Computation and meaning of the *b*-value estimation errors In this section we show the b-value time series of TABOO catalog and their related estimation errors, 36 37 expressed in terms of standard deviation, referring both to the entire catalog and to the background and clustered seismicity components (Figure S3). The "Weighted Likelihood Method" proposed by 38 Taroni *et al.* (2021a) allows in fact to estimate the *b*-value with the respective estimation errors (eq. 39 40 5 in Taroni *et al.* 2021b, using the weighting scheme defined in the "Estimation of the *b*-value in 41 time" subsection within our manuscript). 42 In detail, the errors associated to the *b*-values of both the entire catalog and the two components of 43 seismicity have average value of about  $\pm$  0.12 for the first three years of registration analyzed, while 44 45 it tends to decrease around average value of about  $\pm 0.04$  for the entire catalog and for the triggered

earthquakes in recent years recorded (from about March-April 2013 to December 2015).

The highest errors estimated for the first part of the catalog could be attributable to the lower number of events recorded in these first years, when a number of earthquakes equal to about 1/6 of those present in the whole catalog occurred. Therefore, also the largest *b*-values fluctuations found in this observation period can be attributed to stochastic variations linked to the little amount of data. Starting from the second half of 2013, with the increase in the earthquake occurrences mostly due to the increase of the number of the triggered events, the standard deviations for clustered and global seismicity decrease, while the *b*-value errors for the background show same values in time, probably attributable to the no significant variations in the number of events associated with it.

#### DATA AND RESOURCES

The dataset considered in this work is generated by The Altotiberina Near Fault Observatory

(TABOO), an Istituto Nazionale di Geofisica e Vulcanologia monitoring infrastructure. This

infrastructure is part of the European Plate Observing System - Implementation Phase (EPOS-IP)

project, available at <a href="http://www.epos - eu.org">http://www.epos - eu.org</a>, which received funding from the European Union's

Horizon 2020 research and innovation program under grant agreement 676564.

The *b*-value time series built through the "Weighted Likelihood Approach" were obtained using the

code by Taroni et al. (2021) available at:

<u>GitHub - MatteoTaroniINGV/Bvalue\_TimeSeries\_WeightedLikelihoodEstimation</u>

All the graphs reported in the figures were made using Matlab codes

### REFERENCES FOR THE SUPPLEMENTARY MATERIAL

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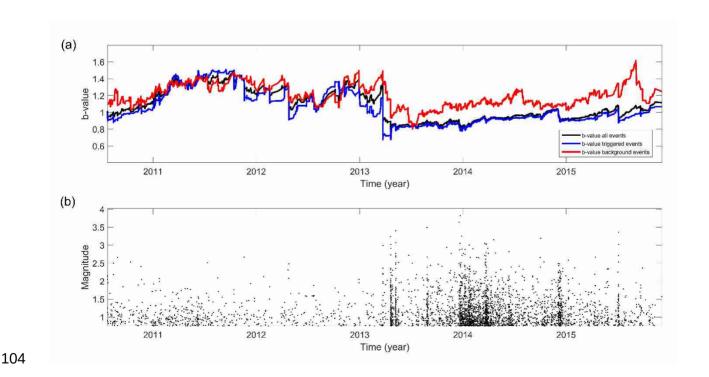
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- 85 *Planets and Space*, **69**(1), 1-12. https://doi.org/10.1186/s40623-017-0614-6
  - **List of Supplemental Figure Captions**

- **Figure S1.** (a) *b*-value time series estimated using the weighted likelihood approach considering a
- magnitude of completeness equal to 0.75. The black line refers to all events recorded in the TABOO
- ocatalog, while the red line and the blue line are the *b*-values for background and clustered seismicity,
- 91 respectively. (b) Magnitude earthquakes distribution over time.

**Figure S2.** (a) *b*-value time series estimated using the weighted likelihood approach considering a magnitude of completeness equal to 1. The black line refers to all events recorded in the TABOO catalog, while the red line and the blue line are the *b*-values for background and clustered seismicity, respectively. (b) Magnitude earthquakes distribution over time.

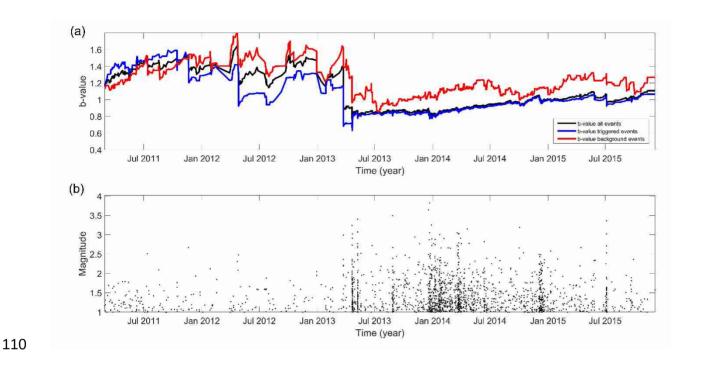
**Figure S3.** (a) *b*-value time series estimated using the weighted likelihood approach considering a magnitude of completeness equal to 0.5. The black line refers to all events recorded in the TABOO catalog, while the red line and the blue line are the *b*-values for background and clustered seismicity, respectively. The *b*-value standard deviation for the entire catalog is indicated by the dashed line while the standard deviations for independent and triggered events are represented by red and blue dashed lines, respectively. (b) Magnitude earthquakes distribution over time.

103 Figures:

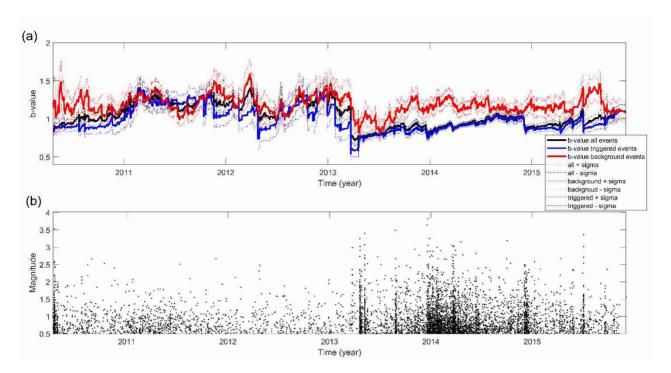


**Figure S1.** (a) *b*-value time series estimated using the weighted likelihood approach considering a magnitude of completeness equal to 0.75. The black line refers to all events recorded in the TABOO

catalog, while the red line and the blue line are the *b*-values for background and clustered seismicity, respectively. (b) Magnitude earthquakes distribution over time.



**Figure S2.** (a) *b*-value time series estimated using the weighted likelihood approach considering a magnitude of completeness equal to 1. The black line refers to all events recorded in the TABOO catalog, while the red line and the blue line are the *b*-values for background and clustered seismicity, respectively. (b) Magnitude earthquakes distribution over time.



**Figure S3**. (a) *b*-value time series estimated using the Weighted Likelihood Approach. The black line refers to all events recorded in the TABOO catalog, while the red line and the blue line are the *b*-values for background and clustered seismicity, respectively. The *b*-value standard deviation for the entire catalog is indicated by the dot line while the standard deviations for independent and triggered events are represented by red and blue dot lines, respectively. (b) Magnitude earthquakes distribution over time.

